

# Diffusion and Cascading Behavior in Networks

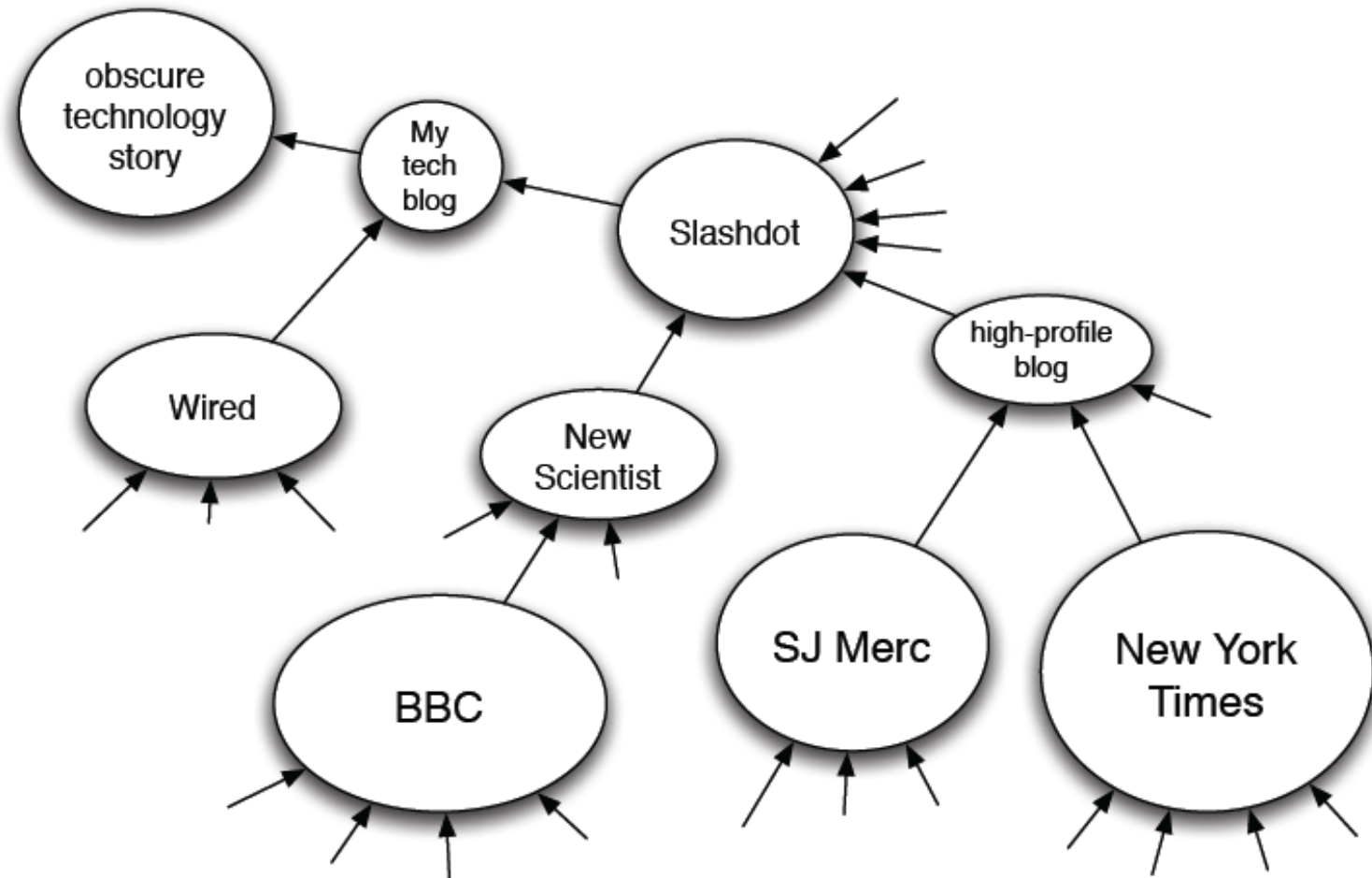
CS224W: Social and Information Network Analysis  
Jure Leskovec, Stanford University  
<http://cs224w.stanford.edu>



# Spreading Through Networks

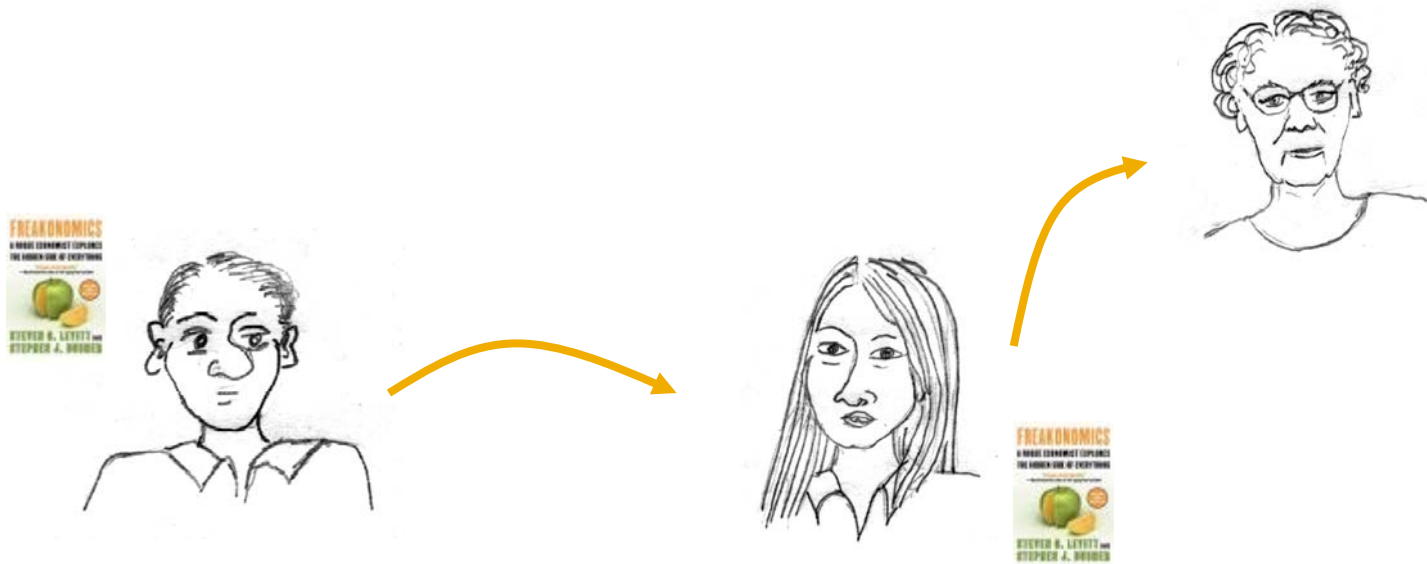
- **Spreading through networks:**
  - Cascading behavior
  - Diffusion of innovations
  - Network effects
  - Epidemics
- **Behaviors that cascade from node to node like an epidemic**
- **Examples:**
  - **Biological:**
    - Diseases via contagion
  - **Technological:**
    - Cascading failures
    - Spread of information
  - **Social:**
    - Rumors, news, new technology
    - Viral marketing

# Information Diffusion

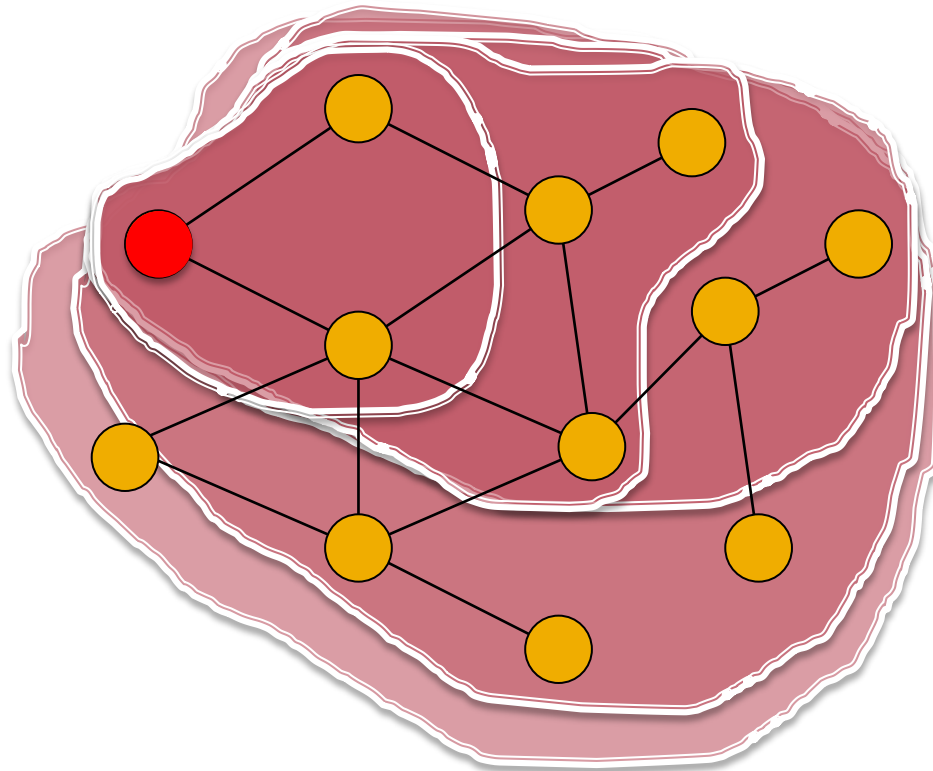


# Diffusion in Viral Marketing

- **Product adoption:**
  - **Senders and followers of recommendations**

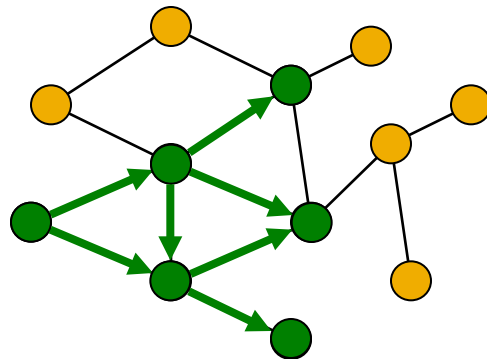


# Spread of Diseases

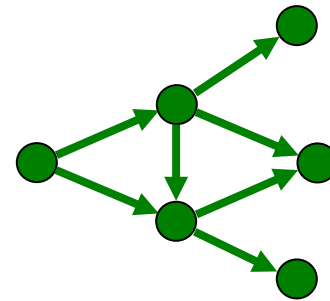


# Network Cascades

- Behavior/contagion spreads over the edges of the network
- It creates a propagation tree, i.e., **cascade**



Network



Cascade

(propagation graph)

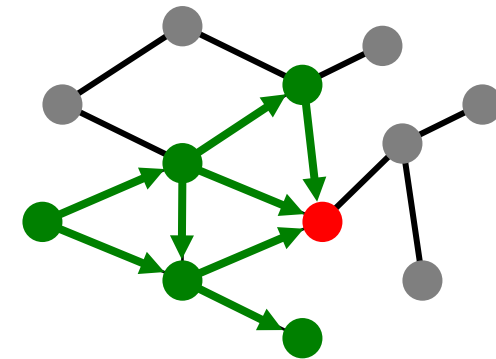
## Terminology:

- Stuff that spreads: Contagion
- “Infection” event: Adoption, infection, activation
- We have: Infected/active nodes, adoptors

# How to Model Diffusion?

## ■ Probabilistic models:

- Models of influence or disease spreading
  - An infected node tries to “push” the contagion to an uninfected node
- **Example:**
  - You “catch” a disease with some prob. from each active neighbor in the network



## ■ Decision based models:

- Models of product adoption, decision making
  - A node observes decisions of its neighbors and makes its own decision
- **Example:**
  - You join demonstrations if  $k$  of your friends do so too

# Decision Based Model of Diffusion

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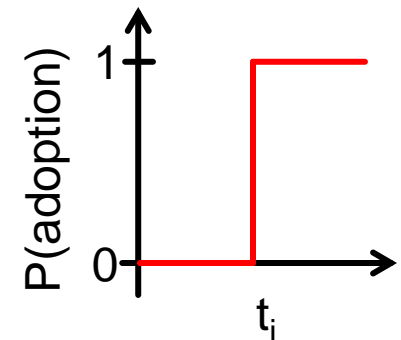


# Decision Based Models

- **Collective Action** [Granovetter, '78]
  - Model where everyone sees everyone else's behavior
  - **Examples:**
    - Clapping or getting up and leaving in a theater
    - Keeping your money or not in a stock market
    - Neighborhoods in cities changing ethnic composition
    - Riots, protests, strikes

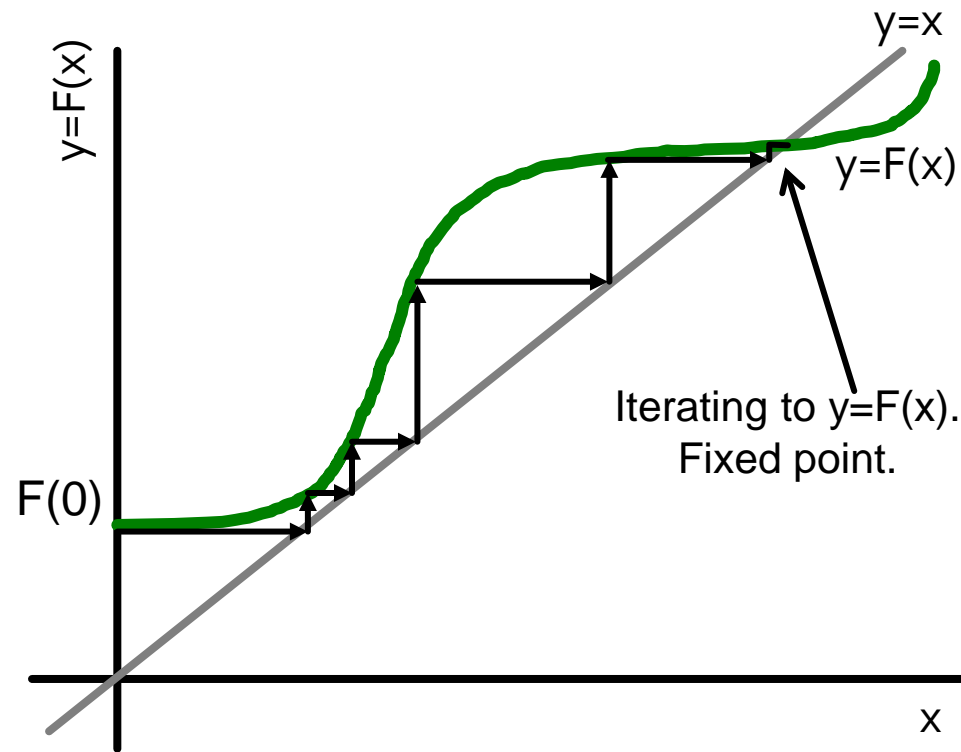
# Collective Action: The Model

- **n people – everyone observes all actions**
- Each person  $i$  has a threshold  $t_i$ 
  - Node  $i$  will adopt the behavior iff at least  $t_i$  other people are adopters:
    - **Small  $t_i$ :** early adopter
    - **Large  $t_i$ :** late adopter
- **The population is described by  $\{t_1, \dots, t_n\}$** 
  - **$F(x)$  ... fraction of people with threshold  $t_i \leq x$**



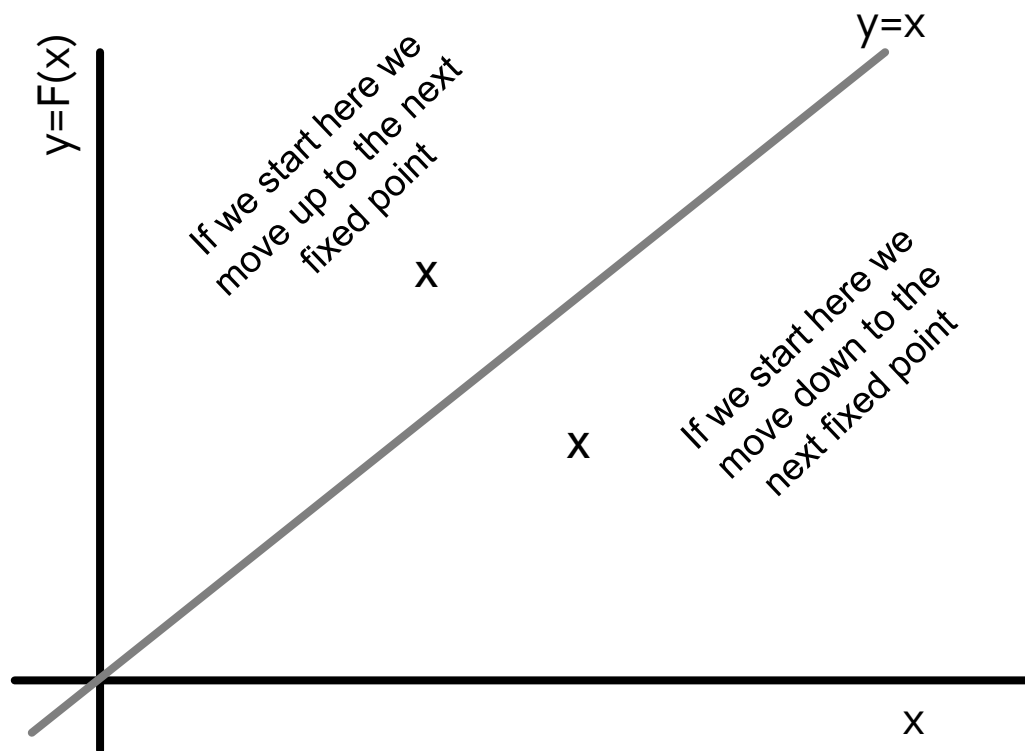
# Collective action: Dynamics

- Think of the step-by-step change in number of people adopting the behavior:
  - $F(x)$  ... fraction of people with threshold  $\leq x$
  - $s(t)$  ... number of participants at time  $t$
- Easy to simulate:
  - $s(0) = 0$
  - $s(1) = F(0)$
  - $s(2) = F(s(1)) = F(F(0))$
  - $s(t+1) = F(s(t)) = F^{t+1}(0)$
- Fixed point:  $F(x)=x$ 
  - There could be other fixed points but starting from 0 we never reach them

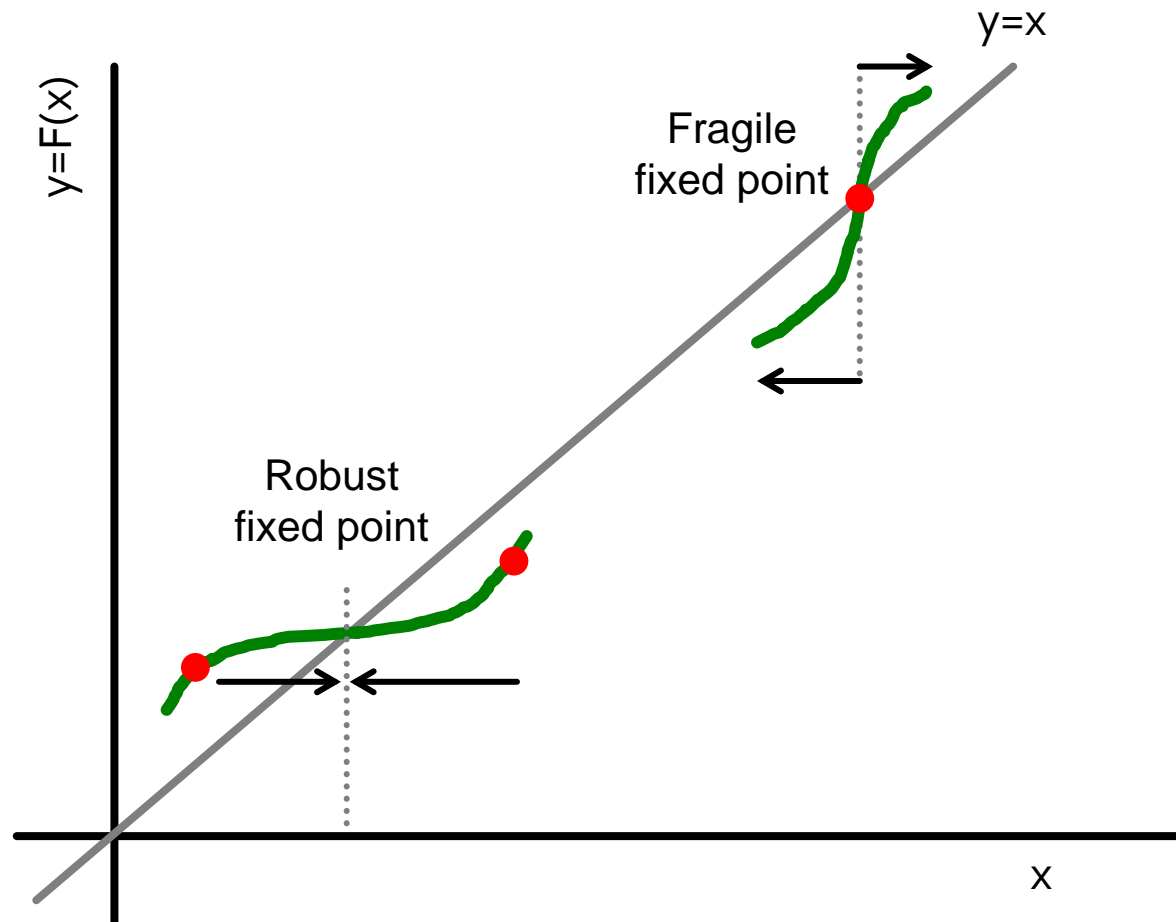


# Starting Elsewhere

- What if we start the process somewhere else?
  - We move up/down to the next fixed point
  - How is market going to change?



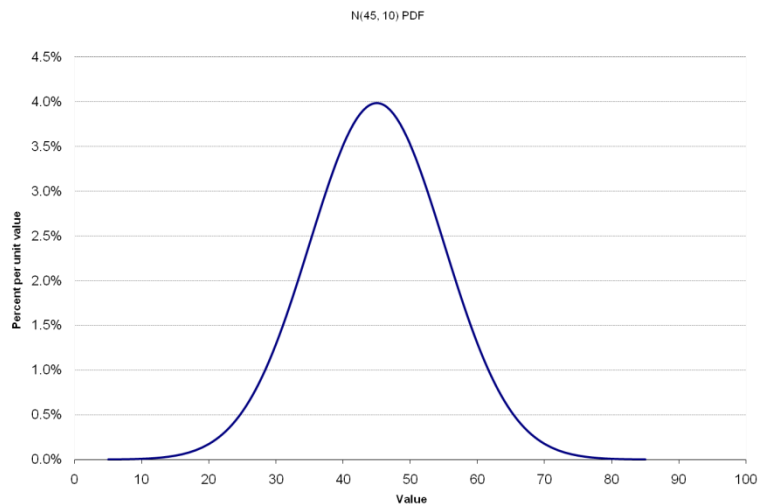
# Fragile vs. Robust Fixed Point



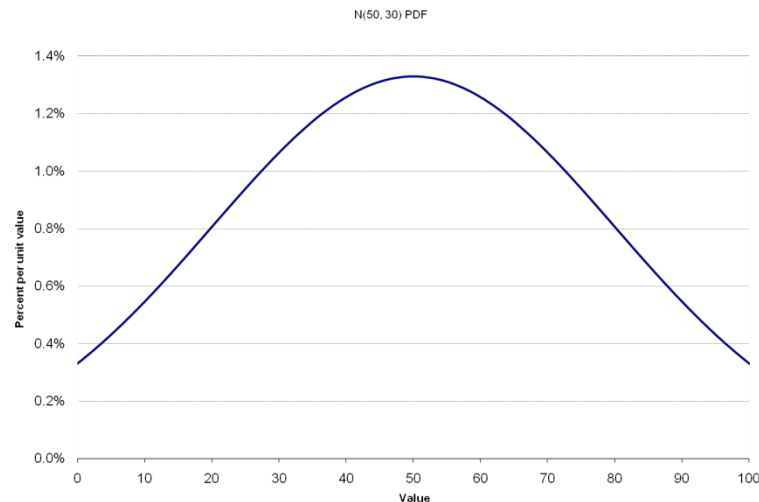
# Discontinuous transition

- Each threshold  $t_i$  is drawn independently from some distribution  $F(x) = Pr[thresh \leq x]$ 
  - **Suppose:** Normal with  $\mu=n/2$ , variance  $\sigma$

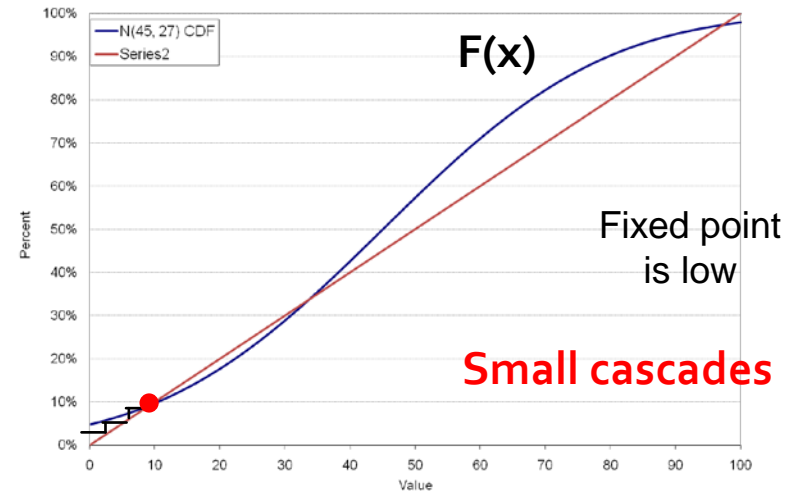
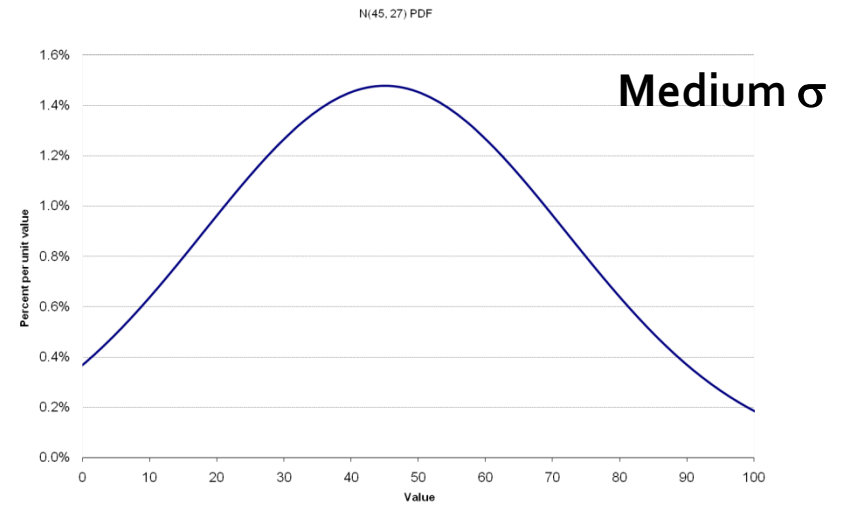
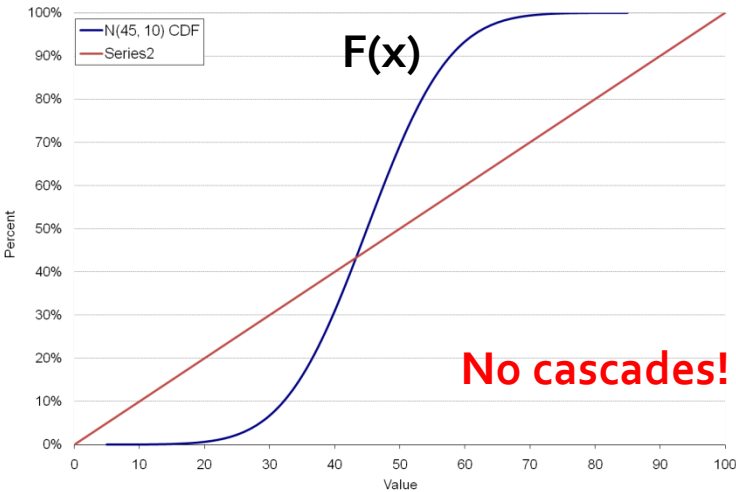
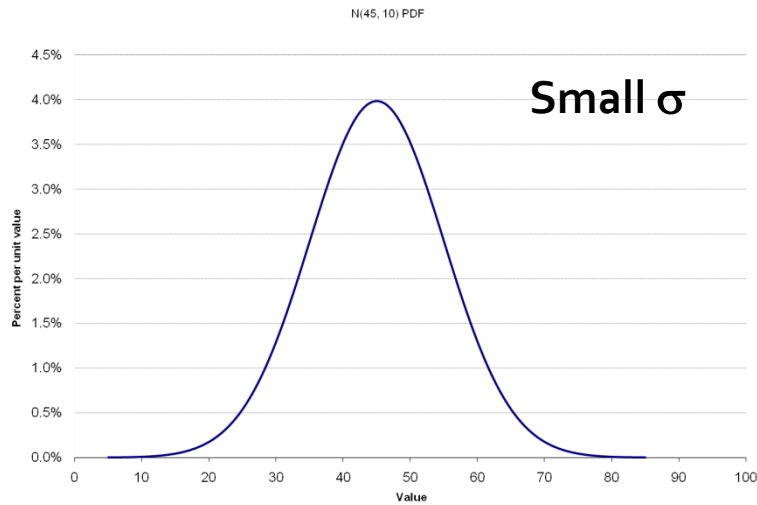
**Small  $\sigma$ :**



**Large  $\sigma$ :**

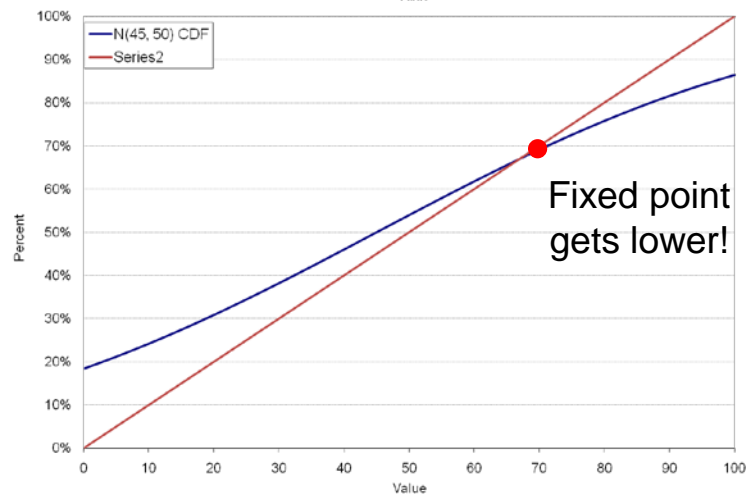
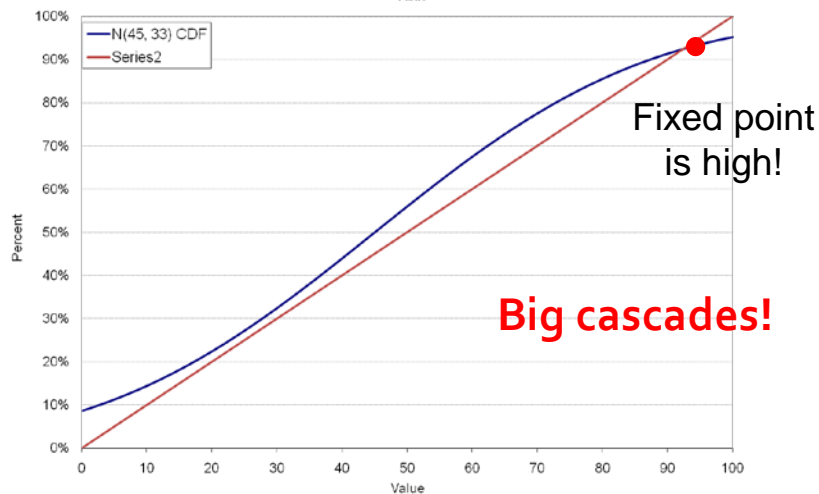
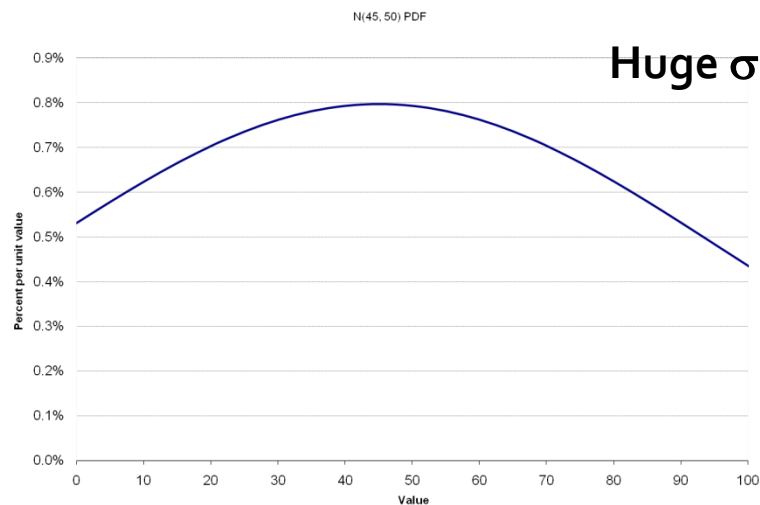
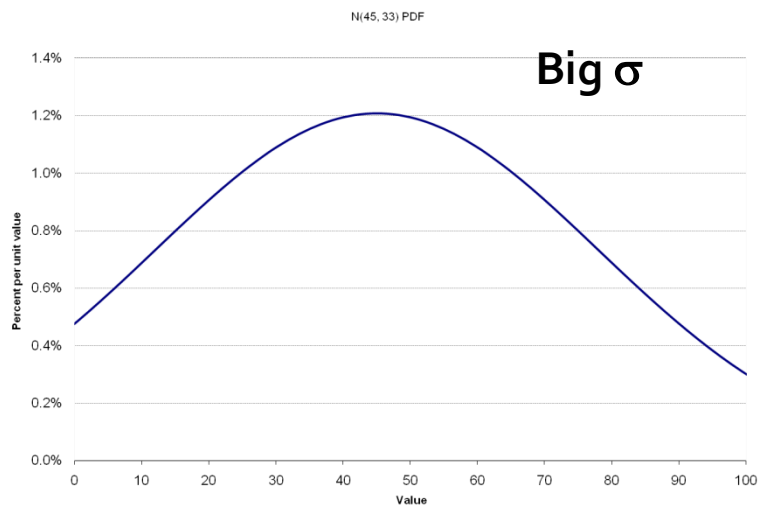


# Discontinuous transition



Bigger variance let's you build a bridge from early adopters to mainstream

# Discontinuous transition



But if we increase the variance even more we move the higher fixed point lower



# Weaknesses of the model

- **It does not take into account:**
  - No notion of social network – more influential users
  - It matters who the early adopters are, not just how many
  - Models people's awareness of size of participation not just actual number of people participating
  - **Modeling thresholds**
    - Richer distributions
    - Deriving thresholds from more basic assumptions
      - game theoretic models

# Weaknesses of the model

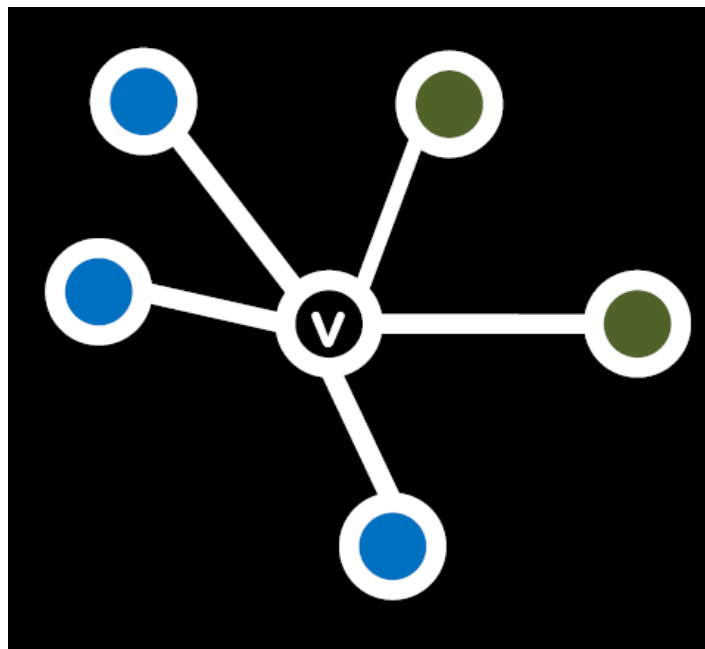
- It does not take into account:
  - Modeling perceptions of who is adopting the behavior/ who you believe is adopting
  - Non monotone behavior – dropping out if too many people adopt
  - Similarity – thresholds not based only on numbers
  - People get “locked in” to certain choice over a period of time
- **Network matters!** (next slide)

# Game Theoretic Model of Cascades

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# Game Theoretic Model of Cascades

- **Based on 2 player coordination game**
  - 2 players – each chooses technology A or B
  - Each person can only adopt **one** “behavior”, A or B
  - You gain more payoff if your friend has adopted the **same** behavior as you



Local view of the network of node v

# Example: BlueRay vs. HD DVD



# The Model for Two Nodes

- **Payoff matrix:**

- If both  $v$  and  $w$  adopt behavior  $A$ , they each get payoff  $a > 0$
- If  $v$  and  $w$  adopt behavior  $B$ , they reach get payoff  $b > 0$
- If  $v$  and  $w$  adopt the opposite behaviors, they each get  $0$

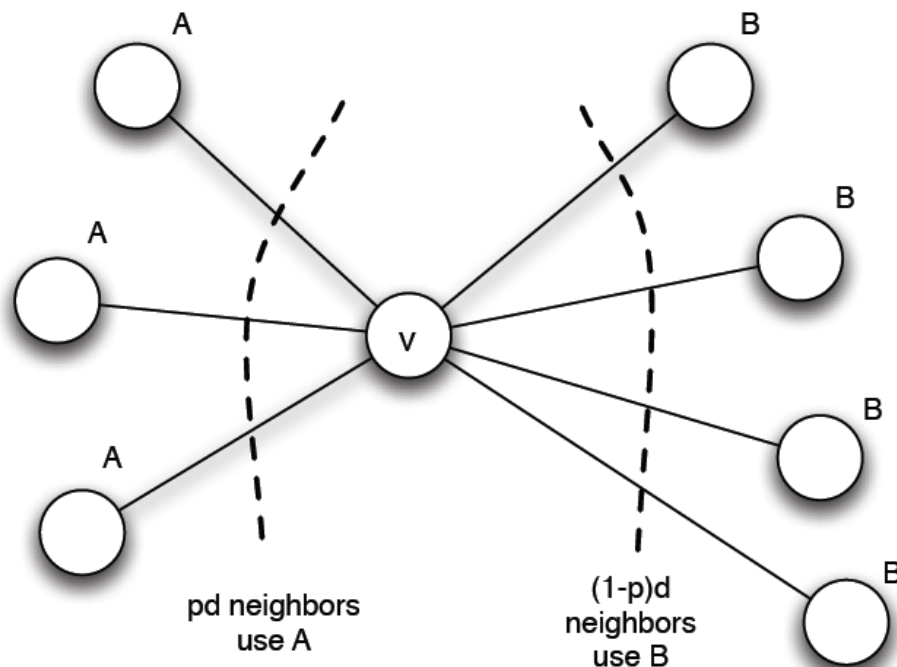


- **In some large network:**

- Each node  $v$  is playing a copy of the game with each of its neighbors
- **Payoff:** sum of node payoffs per game

		$w$	
		$A$	$B$
$v$	$A$	$a, a$	$0, 0$
	$B$	$0, 0$	$b, b$

# Calculation of Node $v$



**Threshold:**

$v$  chooses  $A$  if  $p > q$

$$q = \frac{b}{a + b}$$

- Let  $v$  have  $d$  neighbors
- Assume fraction  $p$  of  $v$ 's neighbors adopt  $A$ 
  - $Payoff_v = a \cdot p \cdot d$  if  $v$  chooses  $A$
  - $= b \cdot (1-p) \cdot d$  if  $v$  chooses  $B$
- **Thus:  $v$  chooses  $A$  if:  $a \cdot p \cdot d > b \cdot (1-p) \cdot d$**

# Example Scenario

- **Scenario:**

Graph where everyone starts with B.

Small set  $S$  of early adopters of A

- Hard wire  $S$  – they keep using A no matter what payoffs tell them to do

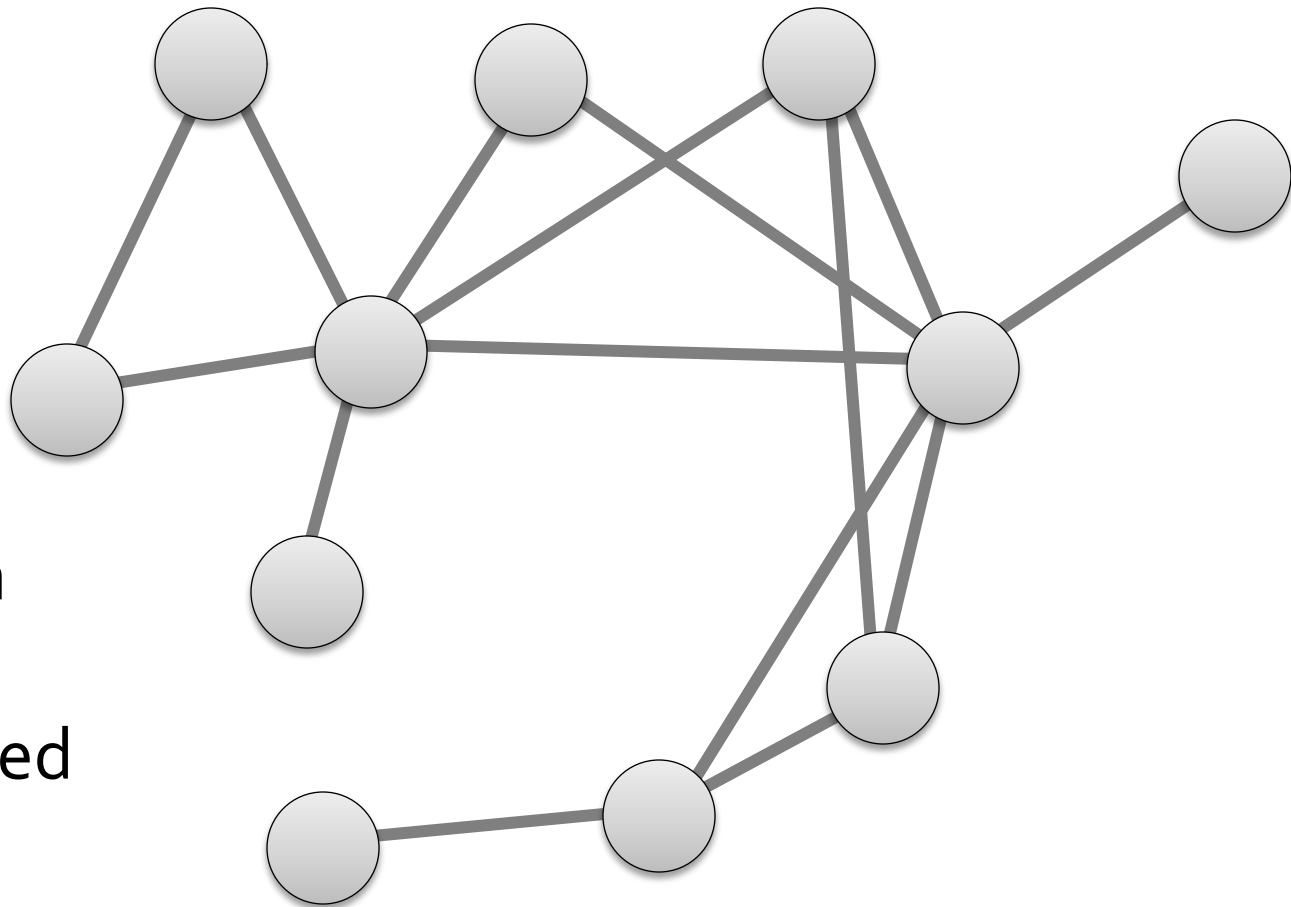
- Payoffs are set in such a way that nodes say:  
**If at least 50% of my friends are red I'll be red**

(this means:  $a = b + \epsilon$ )



# Example Scenario

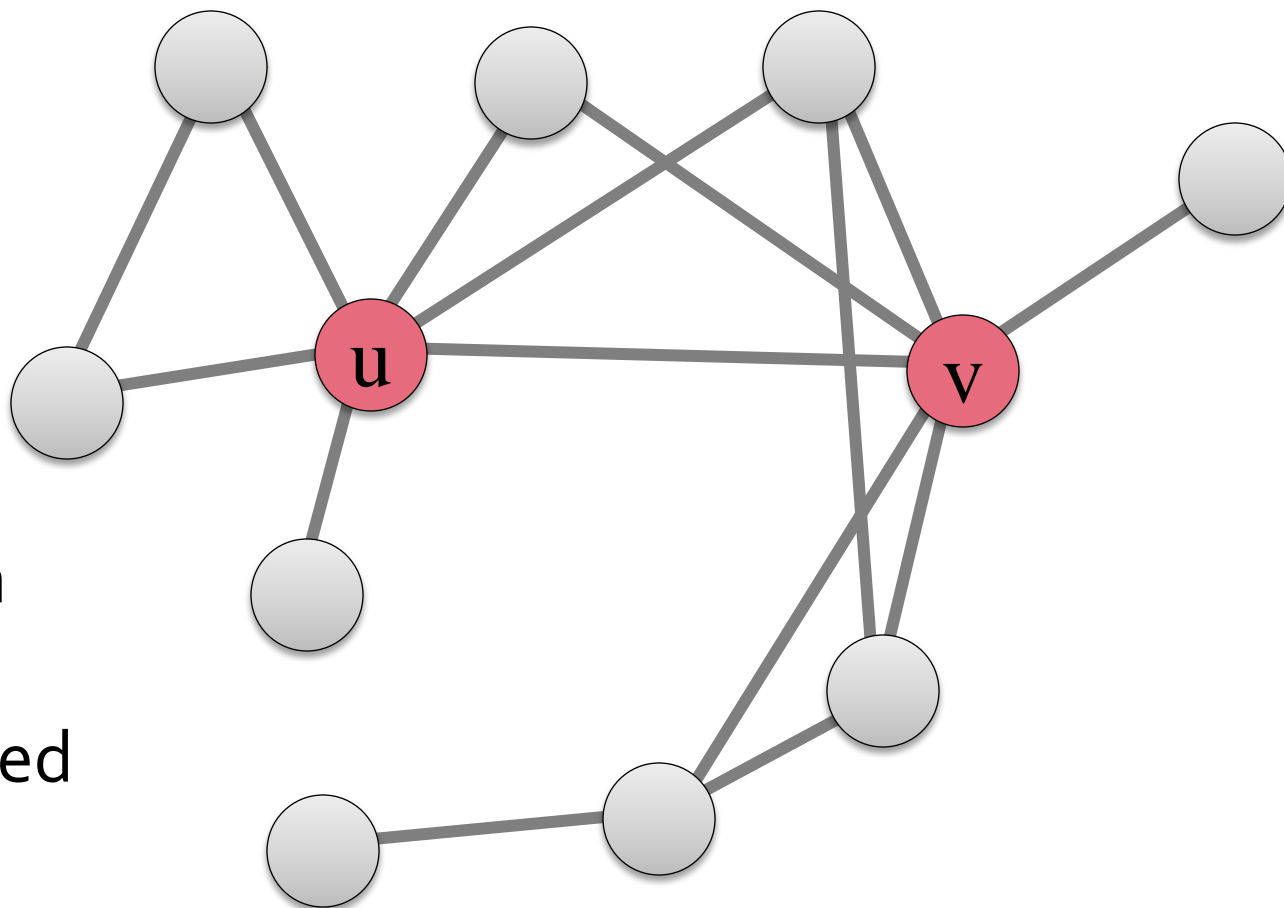
$$S = \{u, v\}$$



If **more** than  
50% of my  
friends are red  
I'll be red

# Example Scenario

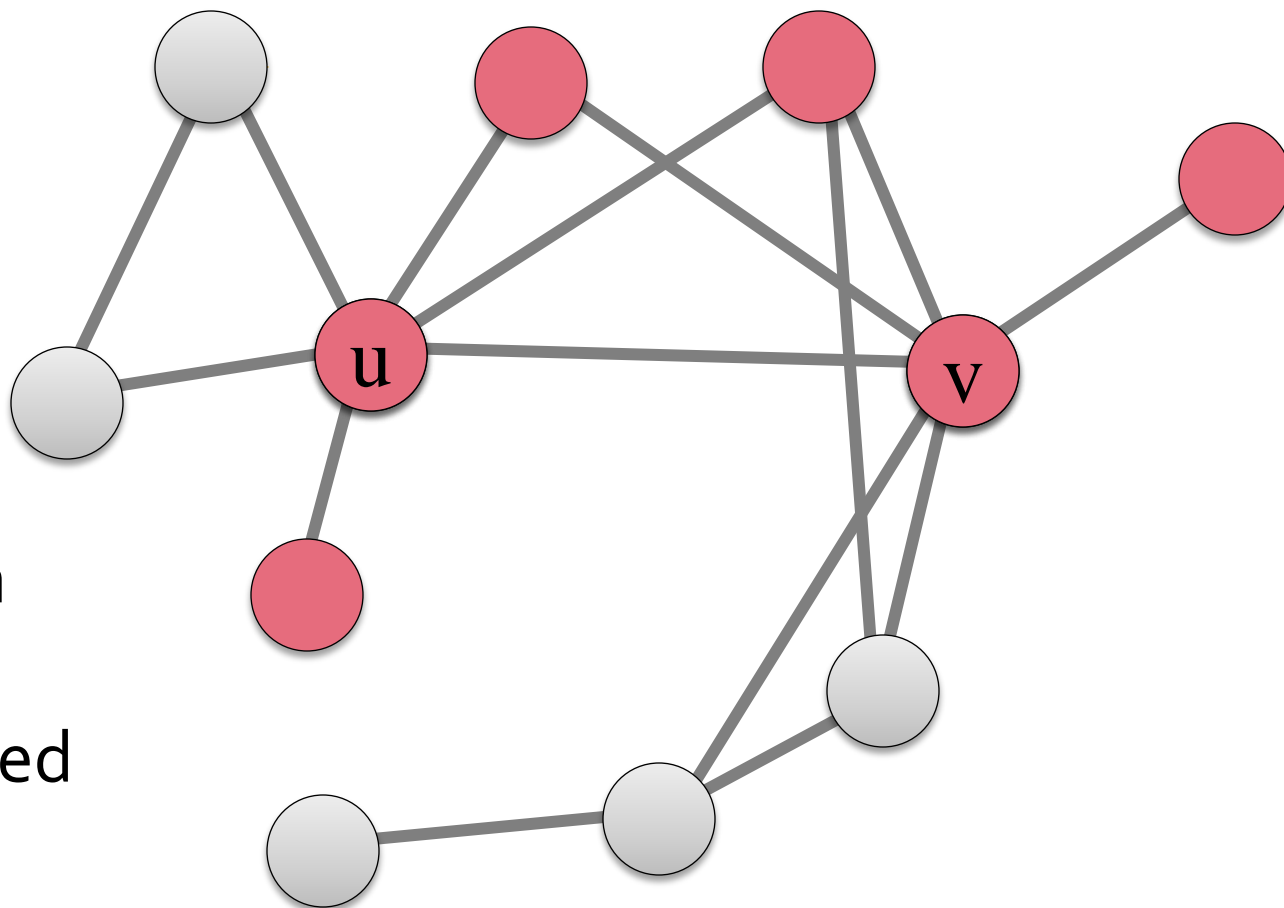
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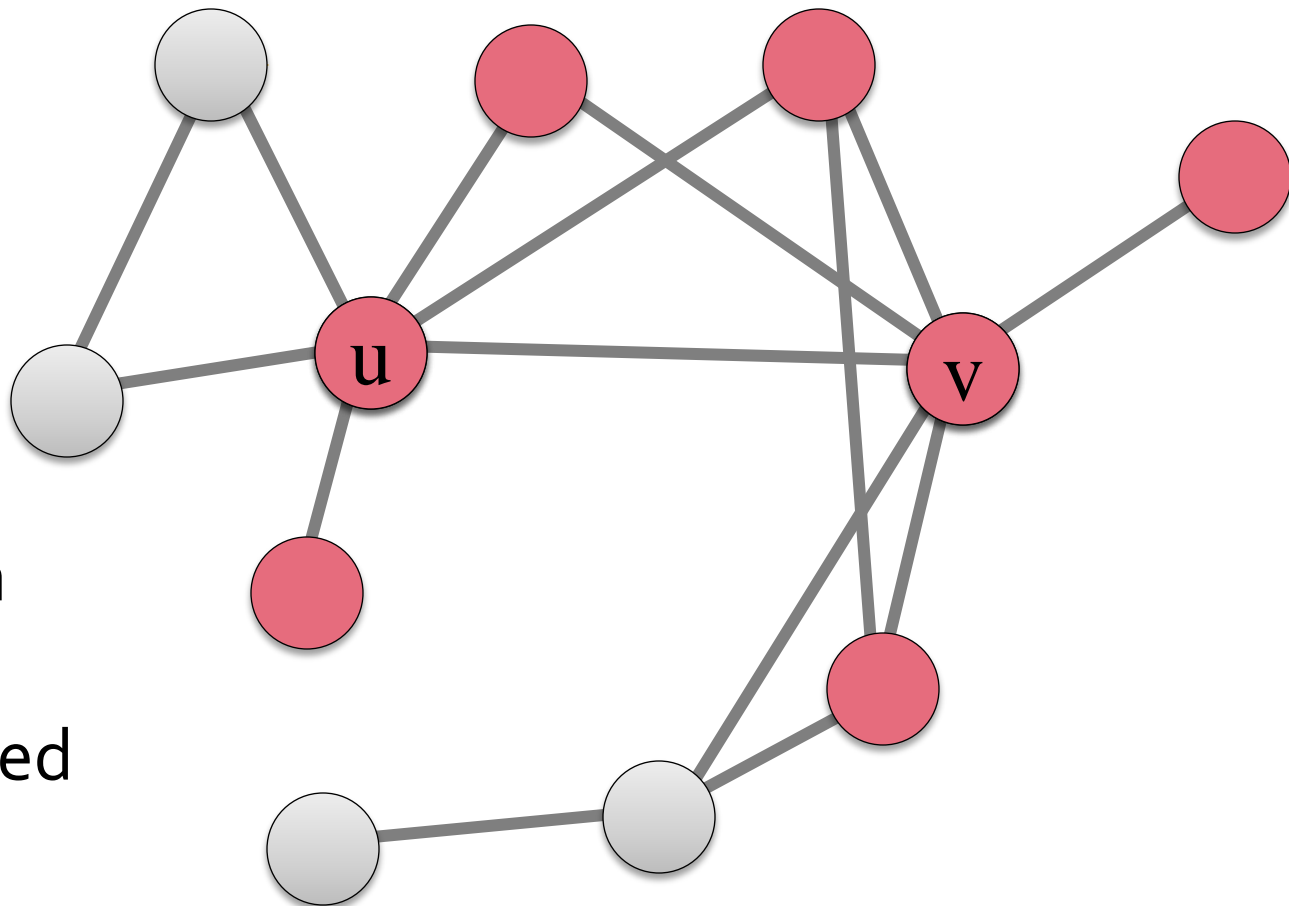
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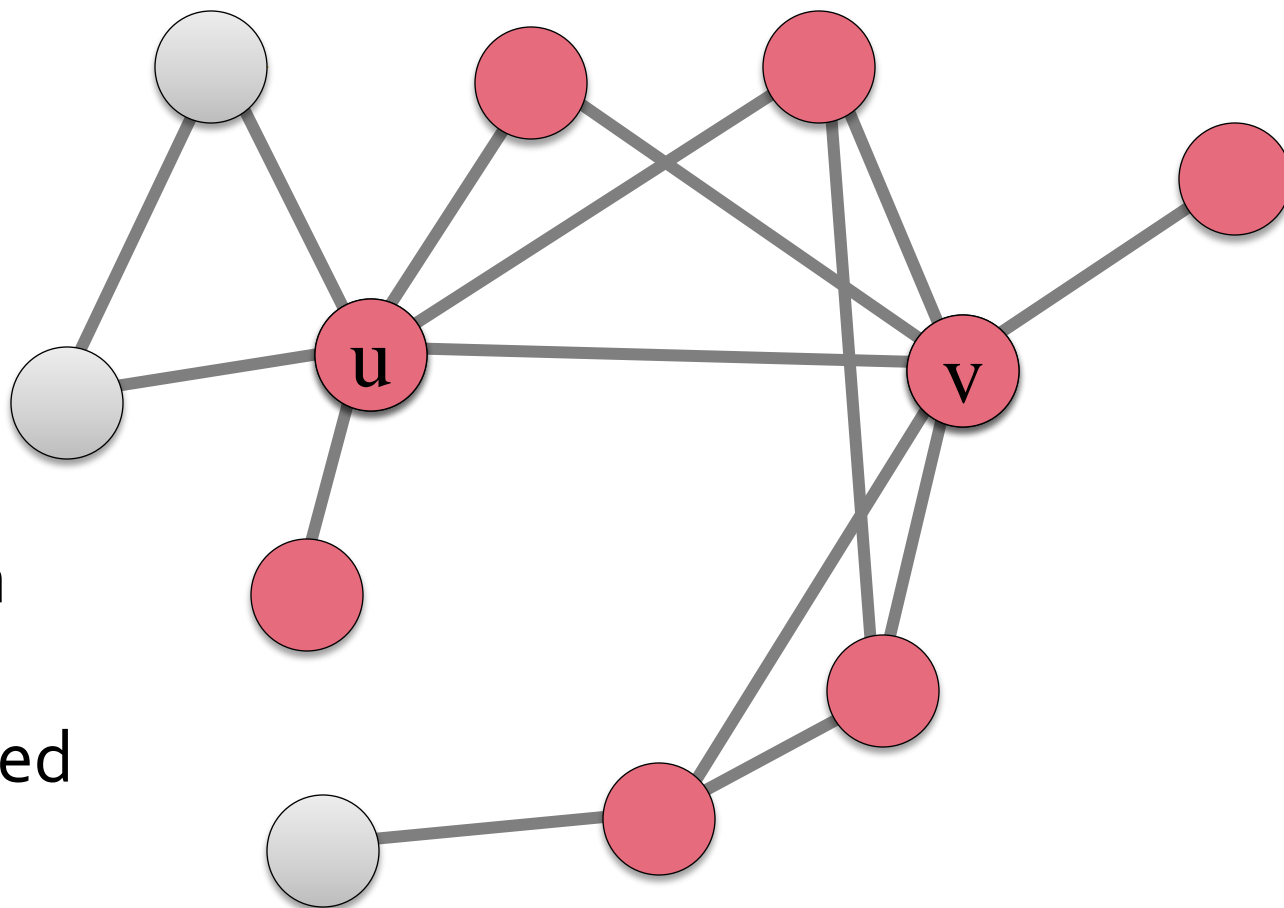
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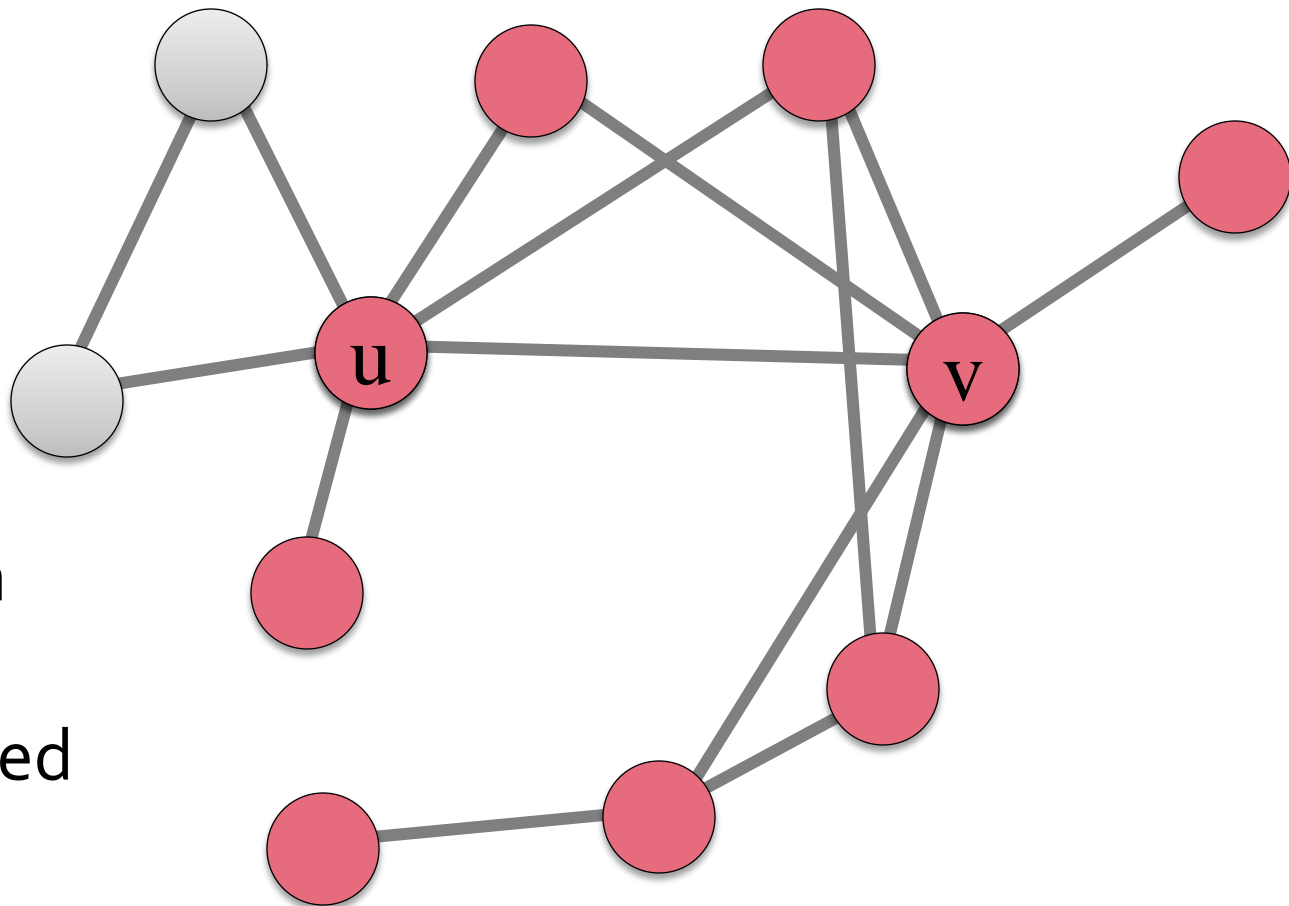
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# Example Scenario

$$S = \{u, v\}$$



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# Monotonic Spreading

- **Observation:**
  - **The use of A spreads monotonically**  
(Nodes only switch from B to A, but never back to B)
- **Why?** Proof sketch:
  - **Nodes keep switching from B to A:**  $B \rightarrow A$
  - Now, suppose some node switched back from  $A \rightarrow B$ , consider the **first** node  $v$  to do so (say at time  $t$ )
  - Earlier at time  $t'$  ( $t' < t$ ) the same node  $v$  switched  $B \rightarrow A$
  - So at time  $t'$   $v$  was above threshold for A
  - But up to time  $t$  no node switched back to B, so node  $v$  could only had more neighbors who used A at time  $t$  compared to  $t'$ . **There was no reason for  $v$  to switch.**

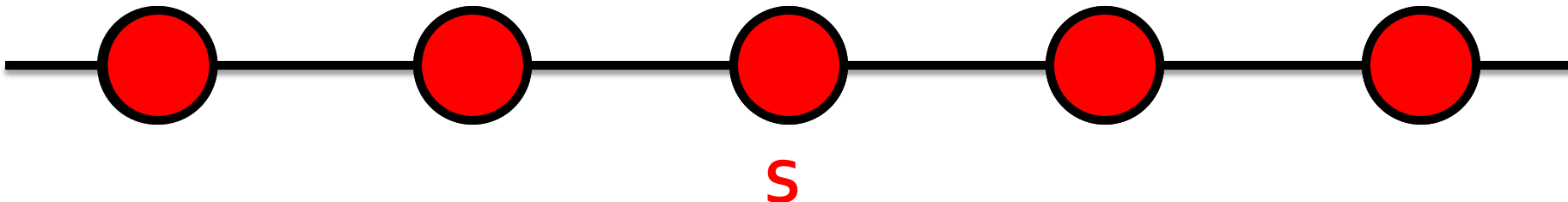
**!! Contradiction !!**

# Infinite Graphs

- Consider infinite graph  $G$ 
  - (but each node has finite number of neighbors)
- We say that a finite set  $S$  causes a cascade in  $G$  with threshold  $q$  if, when  $S$  adopts  $A$ , eventually every node adopts  $A$
- Example: **Path**

$$v \text{ chooses } A \text{ if } p > q$$
$$q = \frac{b}{a+b}$$

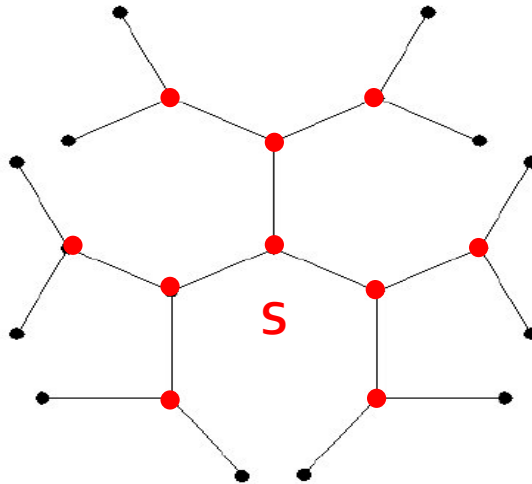
If  $q < 1/2$  then cascade occurs





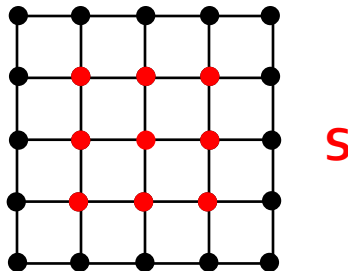
# Infinite Graphs

- Infinite Tree:



If  $q < 1/3$  then  
cascade occurs

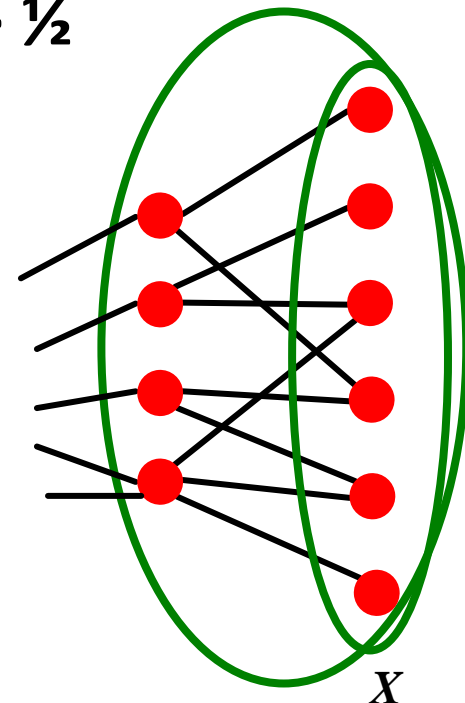
- Infinite Grid:



If  $q < 1/4$  then  
cascade occurs

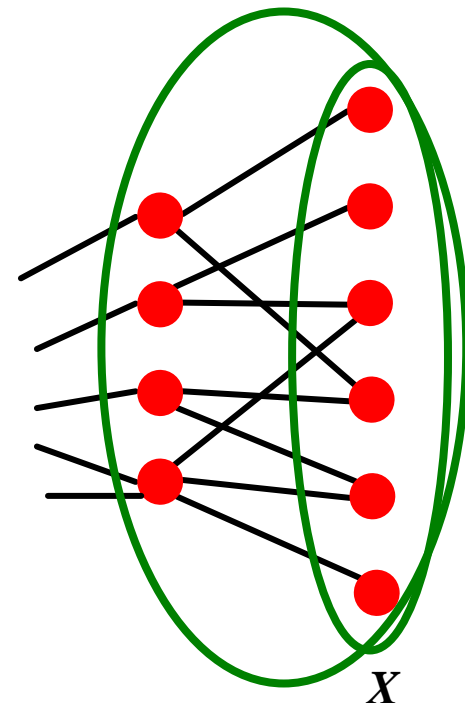
# Cascade Capacity

- Def:
  - The **cascade capacity** of a graph  $G$  is the **largest  $q$**  for which some **finite set  $S$**  can cause a **cascade**
- Fact:
  - There is no  $G$  where cascade capacity  $> \frac{1}{2}$
- **Proof idea:**
  - Suppose such  $G$  exists:  $q > \frac{1}{2}$ , finite  $S$  causes cascade
  - **Show contradiction:** Argue that nodes stop switching after a finite # of steps



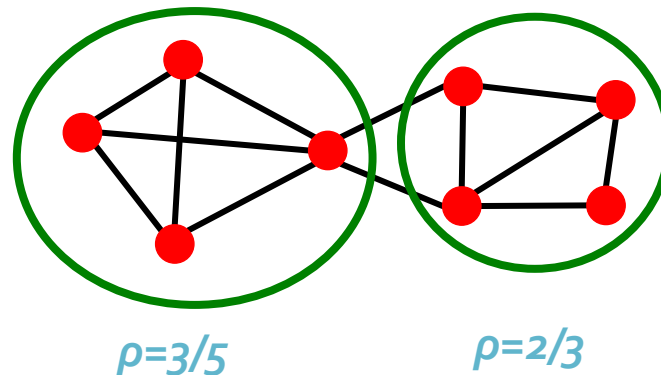
# Cascade Capacity

- **Fact:** There is no  $G$  where cascade capacity  $> \frac{1}{2}$
- **Proof sketch:**
  - Suppose such  $G$  exists:  $q > \frac{1}{2}$ , finite  $S$  causes cascade
  - **Contradiction:** Switching stops after a finite # of steps
    - Define “potential energy”
    - Argue that it starts finite (non-negative) and strictly decreases at every step
  - “Energy”:  $= |d^{\text{out}}(X)|$ 
    - $|d^{\text{out}}(X)| := \#$  of outgoing edges of active set  $X$
    - The only nodes that switch have a strict majority of its neighbors in  $S$
    - $|d^{\text{out}}(X)|$  strictly decreases
    - It can do so only a finite number of steps



# Stopping Cascades

- What prevents cascades from spreading?
- Def: **Cluster of density  $\rho$**  is a **set of nodes  $C$**  where each node in the set has at least  $\rho$  fraction of edges in  $C$ .



# Stopping Cascades

- Let  $S$  be an initial set of adopters of  $A$
- All nodes apply threshold  $q$  to decide whether to switch to  $A$
- **Two facts:**
  - 1) If  $G \setminus S$  contains a cluster of density  $>(1-q)$  then  $S$  can not cause a cascade
  - 2) If  $S$  fails to create a cascade, then there is a cluster of density  $>(1-q)$  in  $G \setminus S$

**Extending the model:  
Allow people to adopt A and B**

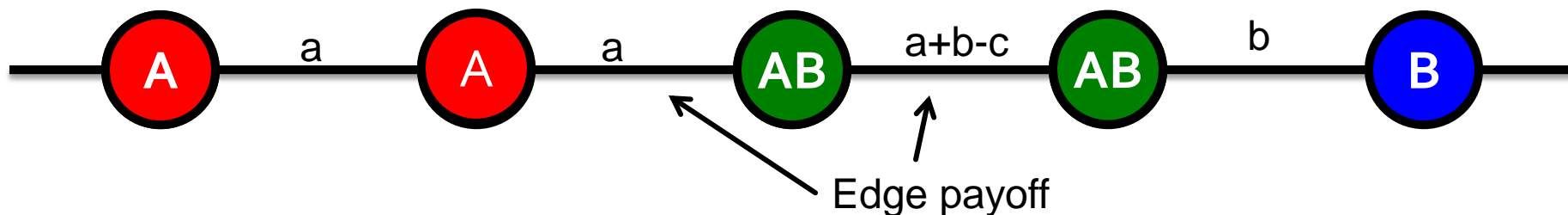
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# Cascades & Compatibility

- **So far:**
  - Behaviors  $A$  and  $B$  compete
  - Can only get utility from neighbors of same behavior:  $A-A$  get  $a$ ,  $B-B$  get  $b$ ,  $A-B$  get  $0$
- **Let's add extra strategy "A-B"**
  - $AB-A$ : gets  $a$
  - $AB-B$ : gets  $b$
  - $AB-AB$ : gets  $\max(a, b)$
  - **Also:** Some **cost**  $c$  for the effort of maintaining both strategies (summed over all interactions)

# Cascades & Compatibility: Model

- Every node in an infinite network starts with  $B$
- Then a finite set  $S$  initially adopts  $A$
- Run the model for  $t=1,2,3,\dots$ 
  - Each node selects behavior that will optimize payoff (given what its neighbors did in at time  $t-1$ )

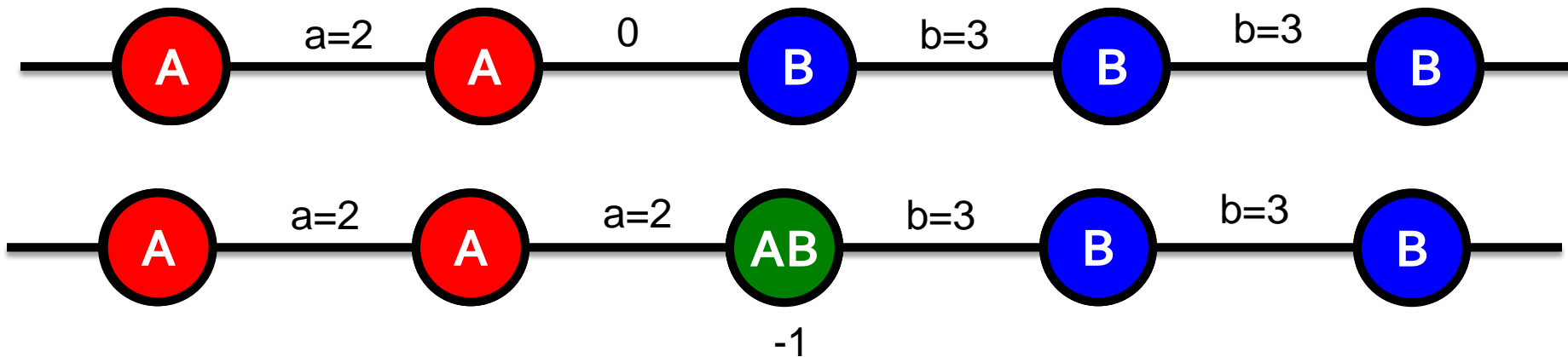


- **How will nodes switch from  $B$  to  $A$  or  $AB$ ?**



# Example

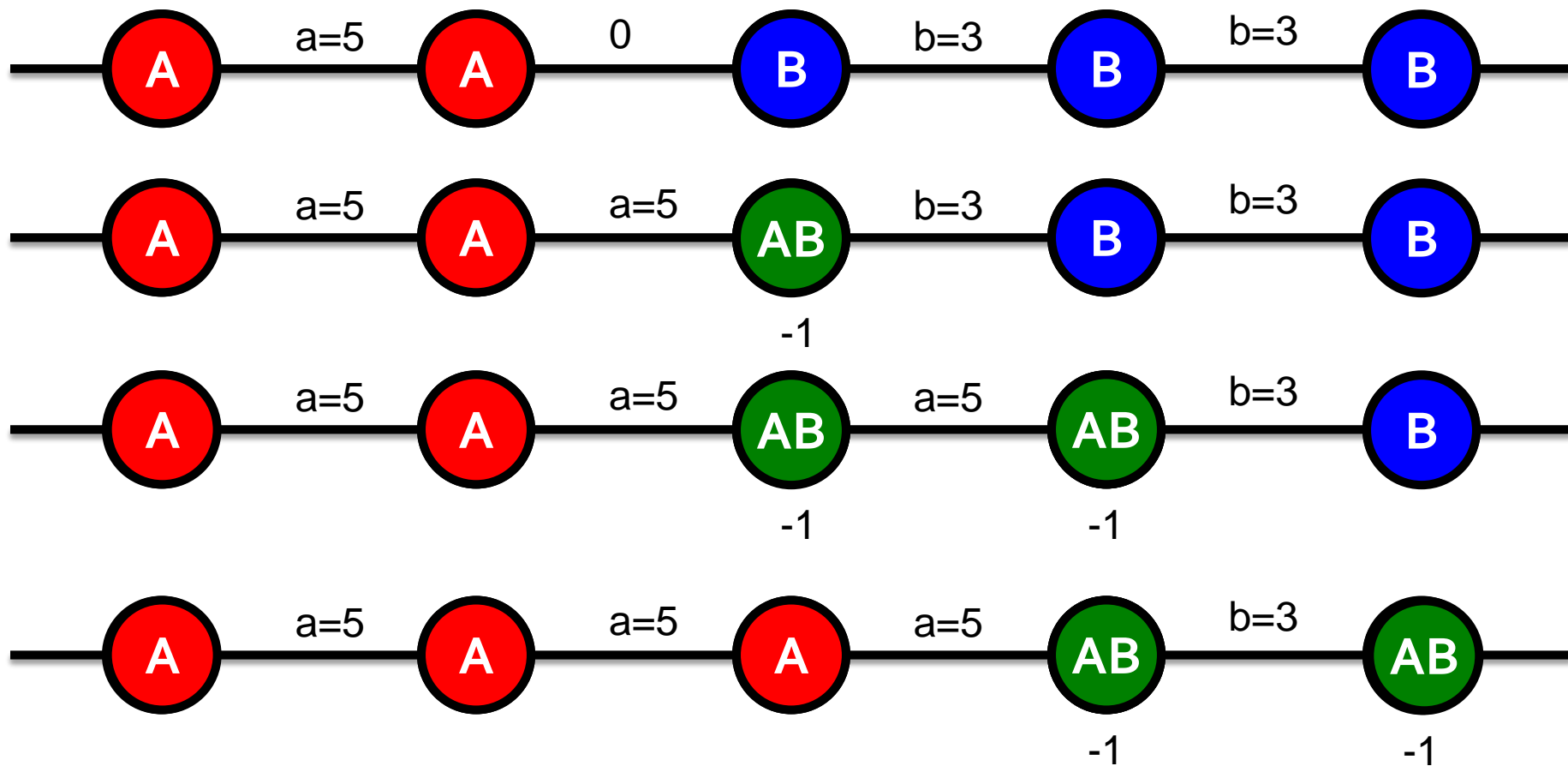
- **Path:** Start with all Bs,  $a > b$  (A is better)
- **One node switches to A – what happens?**
  - With just A, B: A spreads if  $b \leq a$
  - With A, B, AB: **Does A spread?**
- Assume  $a=2, b=3, c=1$



**Cascade stops**

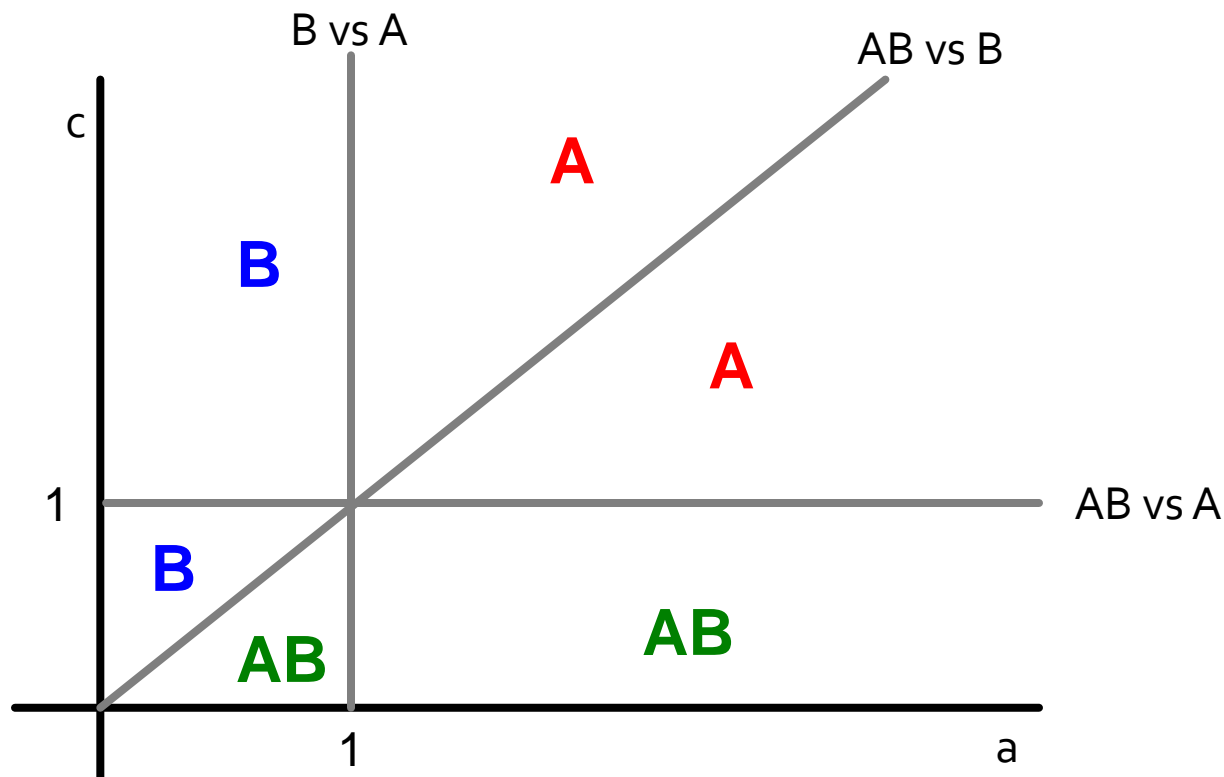
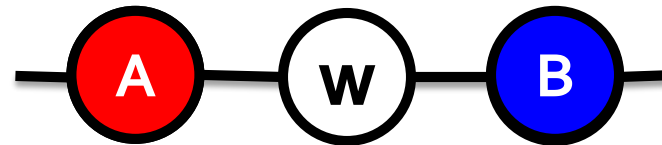
# Example

- Let  $a=5$ ,  $b=3$ ,  $c=1$



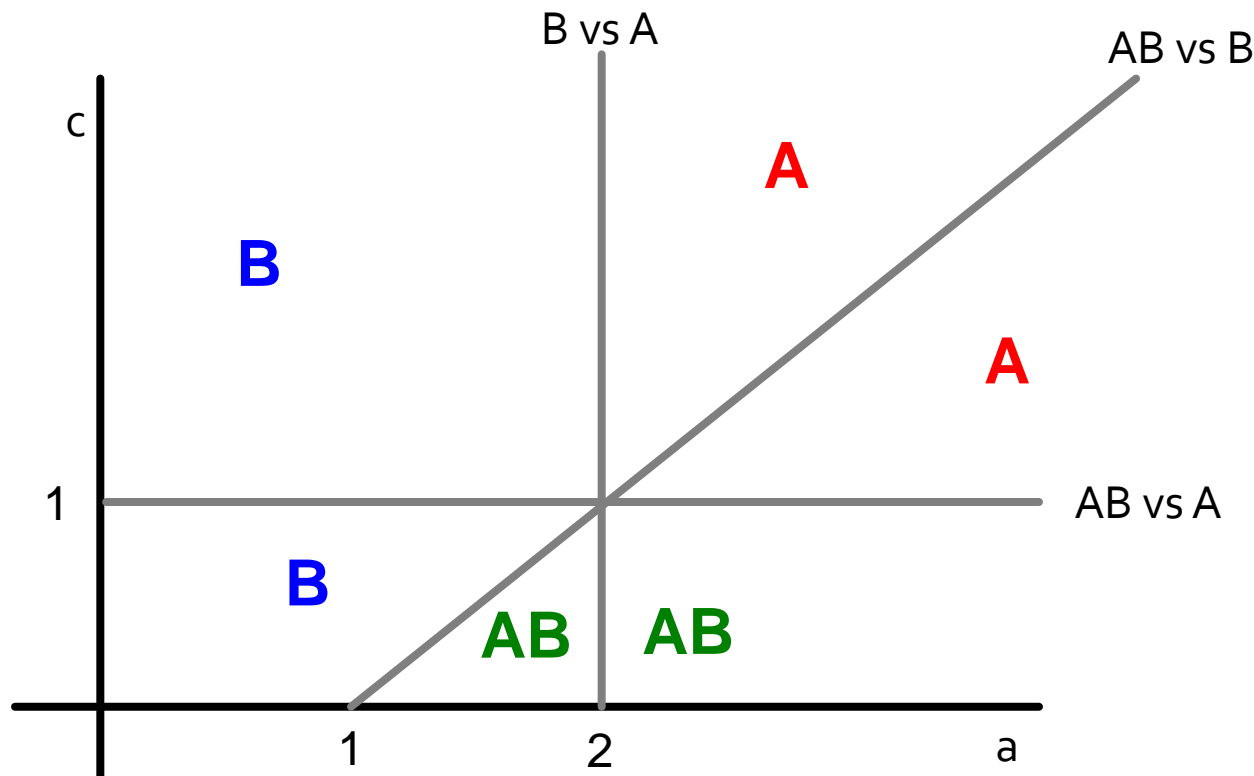
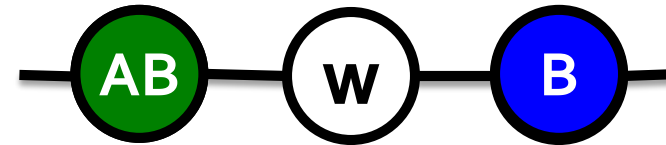
# For what pairs $(c,a)$ does A spread?

- Infinite path, start with all Bs
- **Payoffs:** A: $a$ , B: $1$ , AB: $a+1-c$
- What does node  $w$  in A-w-B do?



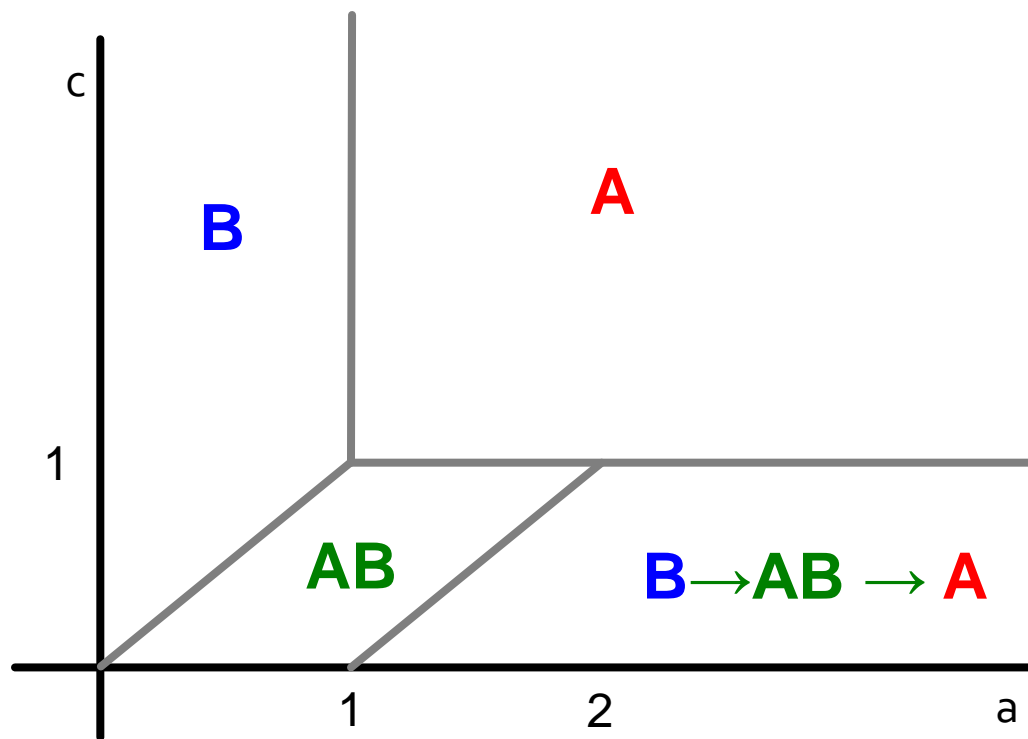
# For what pairs $(c, a)$ does A spread?

- **Payoffs:** A: $a$ , B: $2$ , AB: $a+2-c$
- **Notice:** now also AB spreads
- What does node  $w$  in **AB-w-B** do?



# For what pairs $(c,a)$ does A spread?

- Joining the two pictures:



# Lesson

- You manufacture default B and new/better A comes along:

- Infiltration:** If you make B too compatible then people will take on both and then drop the worse one (B)
- Direct conquest:** If A makes itself not compatible – people on the border must choose. They pick the better one (A)
- Buffer zone:** If you choose an optimal level then you keep a static “buffer” between A and B

