Master Program in *Data Science and Business Informatics* **Statistics for Data Science** Lesson 27 - Bootstrap and resampling methods

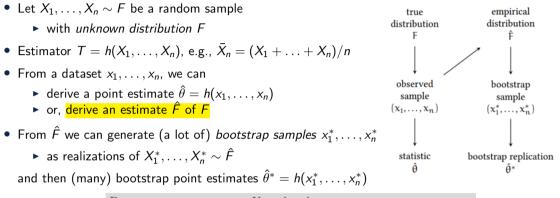
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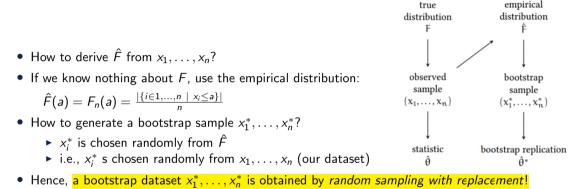
Bootstrap principle

- Let $X_1, \ldots, X_n \sim F$ be a random sample
 - ▶ with unknown distribution F
- Estimator $T = h(X_1, \ldots, X_n)$, e.g., $\bar{X}_n = (X_1 + \ldots + X_n)/n$
 - with unknown (sampling) distribution
- From a dataset x_1, \ldots, x_n , we can derive a point estimate $\hat{ heta} = h(x_1, \ldots, x_n)$
- From many datasets $\{x_1^i, \ldots, x_n^i\}_{i=1}^m$, we can derive many point estimates $\hat{\theta}^i = h(x_1^i, \ldots, x_n^i)$
- By the **Glivenko-Cantelli Thm**, the empirical distribution of $\hat{\theta}^i$ approximates the distribution of T
- Problem: typically, we do not have many datasets, but only one!

Bootstrap principle



BOOTSTRAP PRINCIPLE. Use the dataset x_1, x_2, \ldots, x_n to compute an estimate \hat{F} for the "true" distribution function F. Replace the random sample X_1, X_2, \ldots, X_n from F by a random sample $X_1^*, X_2^*, \ldots, X_n^*$ from \hat{F} , and approximate the probability distribution of $h(X_1, X_2, \ldots, X_n)$ by that of $h(X_1^*, X_2^*, \ldots, X_n^*)$.



- Often the bootstrap approximation of the distribution of *T* will improve if we shift *T* by relating it to a corresponding feature of the "true" distribution.
 - rather than approximating the distribution of X
 _n by the one of X
 _n, better to approximate Δ = X
 _n − μ by Δ* = X
 _n − μ*, where μ* = E[F̂] = x
 _n = (x₁ + ... + x_n)/n [See remarks 18.1 and 18.2 of textbook]

EMPIRICAL BOOTSTRAP SIMULATION (FOR $\bar{X}_n - \mu$). Given a dataset x_1, x_2, \ldots, x_n , determine its empirical distribution function F_n as an estimate of F, and compute the expectation

$$\mu^* = \bar{x}_n = \frac{x_1 + x_2 + \dots + x_n}{n}$$

corresponding to F_n .

- 1. Generate a bootstrap dataset $x_1^*, x_2^*, \ldots, x_n^*$ from F_n .
- 2. Compute the centered sample mean for the bootstrap dataset:

$$\bar{x}_n^* - \bar{x}_n$$

where

$$\bar{x}_n^* = \frac{x_1^* + x_2^* + \dots + x_n^*}{n}$$

Repeat steps 1 and 2 many times.

- Use the empirical distribution of $\delta^* = \bar{x}_n^* \bar{x}_n$ (realizations of $\Delta^* = \bar{X}_n^* \bar{x}_n$)
 - for estimating the distribution of $\Delta = \bar{X}_n \mu$, and in particular:

$$\mathsf{E}[\Delta] = \mathsf{E}[ar{X}_n] - \mu pprox \mathsf{E}[\Delta^*] pprox \mathsf{mean}(\delta^*)$$

• and then estimate μ as $\hat{\mu} = E[\bar{X}_n] - mean(\delta^*) \approx \bar{x}_n - mean(\delta^*)$

 $mean(\delta^*)$ is the estimated bias

▶ and
$$se(\bar{X}_n) = \sqrt{Var(\bar{X}_n)} = \sqrt{Var(\bar{X}_n - \mu)} \approx \sqrt{Var(\bar{X}_n^* - \bar{x}_n)} \approx sd(\delta^*)$$

See R script

EMPIRICAL BOOTSTRAP SIMULATION (FOR $\bar{X}_n - \mu$). Given a dataset x_1, x_2, \ldots, x_n , determine its empirical distribution function F_n as an estimate of F, and compute the expectation

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- 1. Generate a bootstrap dataset $x_1^*, x_2^*, \ldots, x_n^*$ from F_n .
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$$\bar{x}_n^* - \bar{x}_n$$

where

$$\bar{x}_n^* = \frac{x_1^* + x_2^* + \dots + x_n^*}{n}.$$

Repeat steps 1 and 2 many times.

- Use the empirical distribution of $\delta^* = \bar{x}_{n-}^* \bar{x}_n$ (realizations of $\Delta^* = \bar{X}_n^* \bar{x}_n$)
 - for estimating the distribution of $\Delta = \overline{X}_n \mu$, and in particular:
 - confidence interval for $\delta = \bar{x}_n \mu$ is $(q_{\alpha/2}, q_{1-\alpha/2})$ of δ^* empirical distribution

•
$$q_{\alpha/2} \leq \delta = \bar{x}_n - \mu \leq q_{1-\alpha/2}$$
 implies c.i. for μ is $(\bar{x}_n - q_{1-\alpha/2}, \bar{x}_n - q_{\alpha/2})$

boot.ci method in R confidence intervals:

- type='basic': $(\bar{x}_n q_{1-\alpha/2}, \bar{x}_n q_{\alpha/2})$ with quantiles over the distribution of δ^*
- type='perc': $(q_{\alpha/2}, q_{1-\alpha/2})$ with quantiles over the distribution of \bar{x}_n^* (without shift)
- type='norm': $(\bar{x}_n q_{1-\alpha/2}, \bar{x}_n q_{\alpha/2})$ with quantiles over $N(mean(\delta^*), var(\delta^*))$
- type='bca': bias (and skewness) correction and acceleration

boot.ci method in R confidence intervals:

• type='stud':
$$(\bar{x}_n - q_{1-\alpha/2}\frac{s_n}{\sqrt{n}}, \bar{x}_n - q_{\alpha/2}\frac{s_n}{\sqrt{n}})$$
 with quantiles over the distribution of t^*

EMPIRICAL BOOTSTRAP SIMULATION FOR THE STUDENTIZED MEAN. Given a dataset x_1, x_2, \ldots, x_n , determine its empirical distribution function F_n as an estimate of F. The expectation corresponding to F_n is $\mu^* = \bar{x}_n$.

- 1. Generate a bootstrap dataset $x_1^*, x_2^*, \ldots, x_n^*$ from F_n .
- 2. Compute the studentized mean for the bootstrap dataset:

$$\bar{s}^* = \frac{\bar{x}_n^* - \bar{x}_n}{s_n^* / \sqrt{n}}$$

where \bar{x}_n^* and s_n^* are the sample mean and sample standard deviation of $x_1^*, x_2^*, \ldots, x_n^*$. Repeat steps 1 and 2 many times.

- Bootstrap approach applies to any estimator, not only the mean
- Example 1: the German Tank problem

$$T_2 = \frac{n+1}{n}M_n - 1 \qquad \qquad E[T_2] = N$$

- Example 2: linear regression coefficients
 - ▶ 95% confidence intervals (assuming $U_i \sim \mathcal{N}(0, \sigma^2)$):

$$\hat{\beta} \pm t_{n-2,0.025} se(\hat{\beta})$$
 $\hat{\alpha} \pm t_{n-2,0.025} se(\hat{\alpha})$

See R script

[see Lesson 19]

[see Lesson 26]

An application: probability of large errors

- Bootstrap principle: for $X \sim F$
 - ▶ the empirical distribution of $\Delta^* = \bar{X}_n^* \bar{x}_n$ approximates the distribution of $\Delta = \bar{X}_n \mu$
- Application: estimate $P_{\mathcal{F}}(|ar{X}_n-\mu|>1)$ as
 - $P_{\hat{F}}(|\bar{X}_n^* \bar{x}_n| > 1)$ and then by the fraction of $\delta^* = \bar{x}_n^* \bar{x}_n$ such that $|\delta^*| > 1$

Wrap up on empirical bootstrap

- How many bootstrap samples?
 - There are $\binom{2n-1}{n-1}$ distinct bootstrap samples
 - Suggested to use at least 1000 bootstrap samples
 - ► Jackknife resampling: bootstrap samples $x_1, \ldots, x_{i-1}, x_{i+1}, \ldots, x_n$, for $i = 1, \ldots, n$
- How good is the approximation by bootstrap?
 - Small perturbation to data-generating process should produce small perturbation of the parameter to estimate (θ)
 - ▶ Problems with extreme values, e.g., percentiles, maximum, etc.

See R script

[Whv?]

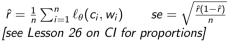
- Decision rule $y_{\theta}^+(w)$ (classifier) or score function $s_{\theta}(w)$ (binary probabilistic classifier, Lesson 23)
- Loss function, e.g., 0-1 loss $\ell_{ heta}(c,w) = \mathbb{1}_{y^+_{ heta}(w)
 eq c}$

Risk (or Expected Prediction Error EPE)

The risk w.r.t. a loss function ℓ_{θ} is $R(\theta_{TRUE}, \theta) = E_{(W,C) \sim f_{\theta_{TRUE}}}[\ell_{\theta}(C, W)].$

Question: how to estimate risk given a dataset?

Holdout method: split dataset into training and test, build y⁺_θ() on training, estimate as the empirical risk on test set (w₁, c₁), ..., (w_n, c_n):





Drawbacks: variability of training/test set, and then of empirical risk estimates

Question: how to estimate risk given a dataset?

- Random sampling: repeat holdout k times, and average the empirical risks: $\hat{r} = \frac{1}{k} \sum_{j=1}^{k} \hat{r}^{j}$ with $\hat{r}^{j} = \frac{1}{n_{j}} \sum_{i=1}^{n_{j}} \ell_{\theta}(c_{i}^{j}, w_{i}^{j})$ is the error on j^{th} training-test split
- Standard error calculated as standard deviation over the k repetitions:

$$se = \sqrt{rac{1}{k-1}\sum_{j=1}^{k}(\hat{r}^{j}-\hat{r})^{2}}$$

Wrong! As test sets (and then \hat{r}^{j} 's) are not independent!

Question: how to estimate risk given a dataset?

- k-fold cross-validation: average the empirical risks over k-fold splits: $\hat{r} = \frac{1}{k} \sum_{j=1}^{\kappa} \hat{r}^{j} \text{ with } \hat{r}^{j} = \frac{1}{n/k} \sum_{i=1}^{n/k} \ell_{\theta}(c_{i}^{j}, w_{i}^{j})$ Standard deviation calculated over the k folds, with $se = \sqrt{\frac{1}{k-1} \sum_{j} (\hat{r}^{j} - \hat{r})^{2}}$ Wrong!(*) Test sets are independent, but training sets (and then \hat{r}^{j} 's) are not! $\hat{r} = \frac{1}{k} \sum_{i=1}^{k} \hat{r}^{j}$ with $\hat{r}^{j} = \frac{1}{n/k} \sum_{i=1}^{n/k} \ell_{\theta}(c_{i}^{j}, w_{i}^{j})$
- Standard deviation calculated over the k folds, with

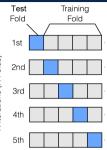
$$se = \sqrt{rac{1}{k-1}\sum_j (\hat{r}^j - \hat{r})^2}$$

• If classifier is stable over the folds (see [Kohavi, 1995]), use:

 $se = \sqrt{\frac{\hat{r}(1-\hat{r})}{n}}$ [see Lesson 26 on CI for proportions]

- Boils down to estimation as holdout but using all data instances (lower variability)!
- ▶ This is the one implemented in R/caret
- Setting k = n is the leave-one out cross-validation (LOOCV)

(*) CV should be treated as an estimator of the average prediction error across training sets!



Question: how to estimate risk given a dataset?

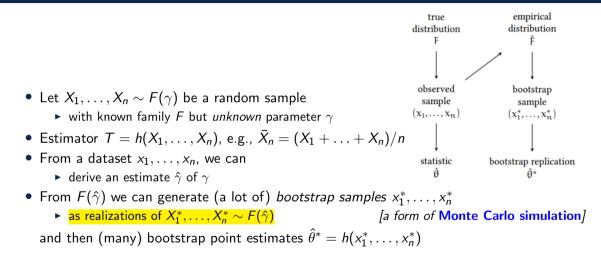
- training = bootstrap x_1^*, \ldots, x_n^* , test = dataset \setminus bootstrap = $\{x_1, \ldots, x_n\} \setminus \{x_1^*, \ldots, x_n^*\}$
 - ▶ .632 **bootstrap algorithm** for *k* bootstrap runs

$$\hat{r} = rac{1}{k} \sum_{j} (0.632 \cdot \hat{r}^{j} + 0.368 \cdot \hat{r}_{tr})$$

where \hat{r}^{j} is the empirical risk on j^{th} bootstrap run, and \hat{r}_{tr} is the empirical risk on the dataset

- [Kohavi, 1995, Kim, 2009] conclusions and recommendations:
 - Bootstrap has low variance, but it is extremely biased
 - ► k-fold cross-validation has low bias and variance can be controlled
 - \Box by averaging multiple *k*-fold cross-validation
 - Recommendation: use repeated (stratified) k-fold cross-validation, with $k \approx 10$
- [Vanwinckelen, 2012] warns against "repeated", and it recommends *k*-fold cross-validation See R script

Parametric bootstrap principle



Parametric bootstrap

PARAMETRIC BOOTSTRAP SIMULATION (FOR $\bar{X}_n - \mu$). Given a dataset x_1, x_2, \ldots, x_n , compute an estimate $\hat{\theta}$ for θ . Determine $F_{\hat{\theta}}$ as an estimate for F_{θ} , and compute the expectation $\mu^* = \mu_{\hat{\theta}}$ corresponding to $F_{\hat{\theta}}$.

- 1. Generate a bootstrap dataset $x_1^*, x_2^*, \ldots, x_n^*$ from $F_{\hat{\theta}}$.
- 2. Compute the centered sample mean for the bootstrap dataset:

$$\bar{x}_n^* - \mu_{\hat{\theta}},$$

where

$$\bar{x}_n^* = \frac{x_1^* + x_2^* + \dots + x_n^*}{n}$$

Repeat steps 1 and 2 many times.

- Cfr with non-parametric bootstrap: use $\mu_{\hat{\theta}}$ instead of \bar{x}_n
- Use the empirical distribution of $\delta^* = \bar{x}^*_n \mu_{\hat{ heta}}$ for estimating
 - confidence interval for $\delta = \bar{x}_n \mu$ is $(q_{\alpha/2}, q_{1-\alpha/2})$ of δ^* empirical distribution

•
$$q_{\alpha/2} \leq \delta = \bar{x}_n - \mu \leq q_{1-\alpha/2}$$
 implies c.i. for μ is $(\bar{x}_n - q_{1-\alpha/2}, \bar{x}_n - q_{\alpha/2})$

Application: distribution fitting

- Consider x_1, \ldots, x_n realizations of a random sample $X_1, \ldots, X_n \sim F$
- Is the dataset from an Exp(λ) for some λ? I.e., is it F = Exp(λ)?
- We estimate $\hat{\lambda} = 1/\bar{x}_n$
- We measure how close is the dataset to the distribution as:

$$t_{ks} = \sup_{a \in \mathbb{R}} |F_n(a) - F_{\hat{\lambda}}(a)|$$

where:

- $F_n(a)$ is the empirical cumulative distribution function of x_1, \ldots, x_n
- $F_{\hat{\lambda}}(a) = 1 e^{\hat{\lambda}a}$, for $a \ge 0$, is the CDF of $Exp(\hat{\lambda})$
- t_{ks} is the Kolmogorov-Smirnov distance
- if $F = Exp(\lambda)$ then both $F_n \approx F$ and $F_{\hat{\lambda}} \approx F$, and then $F_n \approx F_{\hat{\lambda}}$, so that t_{ks} is small
- if $F \neq Exp(\lambda)$ then $F_n \approx F \neq Exp(\lambda) \approx F_{\hat{\lambda}}$, so that t_{ks} is large

[See Lesson 11]

[MLE estimation]

Application: distribution fitting



- $\hat{\lambda} = 0.0015$ and $t_{ks} = 0.17$
- Is $t_{ks} = 0.17$ expected or an extreme value?
- Let's study the distribution of the bootstrap estimator:

true

observed

sample

 $(x_1, ..., x_n)$

where:

- $X_1^*, \dots, X_n^* \sim \textit{Exp}(\hat{\lambda})$ is a bootstrap sample
- $F_n^*(a)$ is the empirical cumulative distribution of the bootstrap sample
- $\hat{\Lambda}^* = 1/\bar{X}_n^*$
- It turns out $P(T_{ks} > 0.17) \approx 0$, unlikely that $Exp(\lambda)$ is the right model See R script

empirical

distribution

bootstrap

sample

 (x_1^*, \dots, x_n^*)

Optional references

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Estimating classification error rate: Repeated Estimating classification error rate: Repeated cross-validation, repeated hold-out and bootstrap.

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Michael R. Chernick and Robert A. LaBudde (2011) An introduction to Bootstrap methods with applications to R. John Wiley & Sons, Inc.