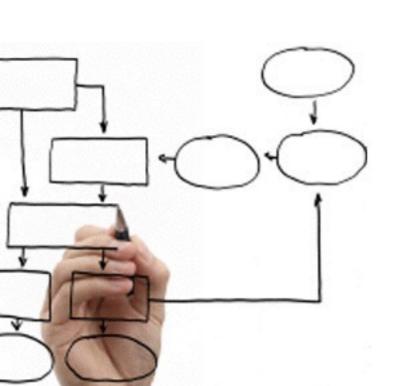
# Methods for the specification and verification of business processes MPB (6 cfu, 295AA)

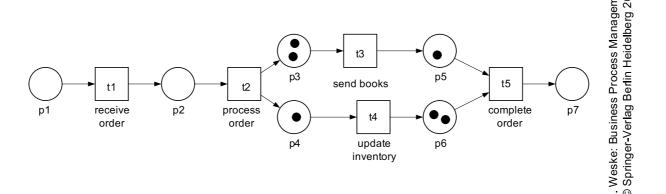


#### Roberto Bruni

http://www.di.unipi.it/~bruni

07 - Introduction to nets

## Object



### Overview of the basic concepts of Petri nets

Free Choice Nets (book, optional reading)

https://www7.in.tum.de/~esparza/bookfc.html

## Why Petri nets?

Business process analysis:

validation: testing correctness

verification: proving correctness

performance: planning and optimization

Use of Petri nets (or alike)
visual + formal
tool supported

### Approaching Petri nets

Are you familiar with automata / transition systems? They are fine for sequential protocols / systems but do not capture concurrent behaviour directly

A Petri net is a mathematical model of a parallel and concurrent system

in the same way that a finite automaton is a mathematical model of a sequential system

### Approaching Petri nets

Petri net theory can be studied at several level of details

We study some basics aspects, relevant to the analysis of business processes

Petri nets have a faithful and convenient graphical representation, that we introduce and motivate next

# Finite automata examples

### Applications

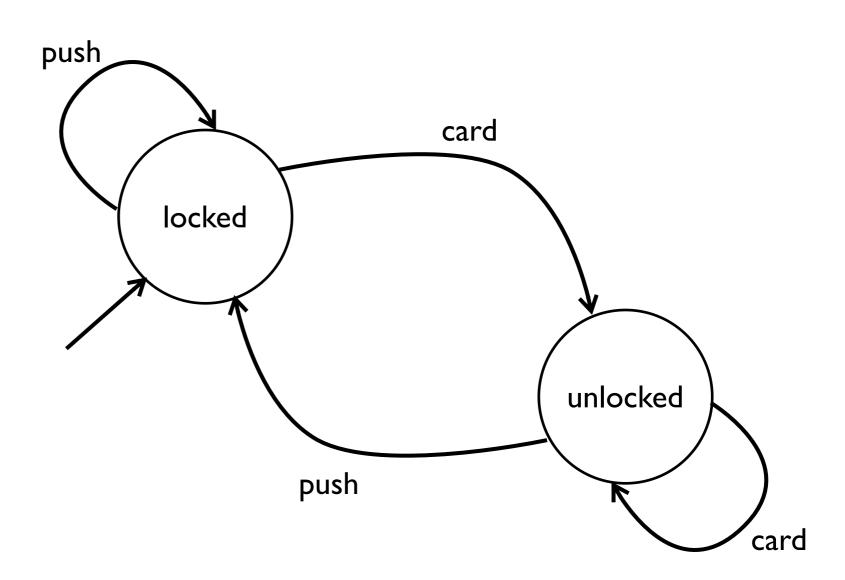
Finite automata are widely used, e.g., in protocol analysis, text parsing, video game character behavior, security analysis, CPU control units, natural language processing, speech recognition, mechanical devices (like elevators, vending machines, traffic lights) and many more ...

## How to define an automaton

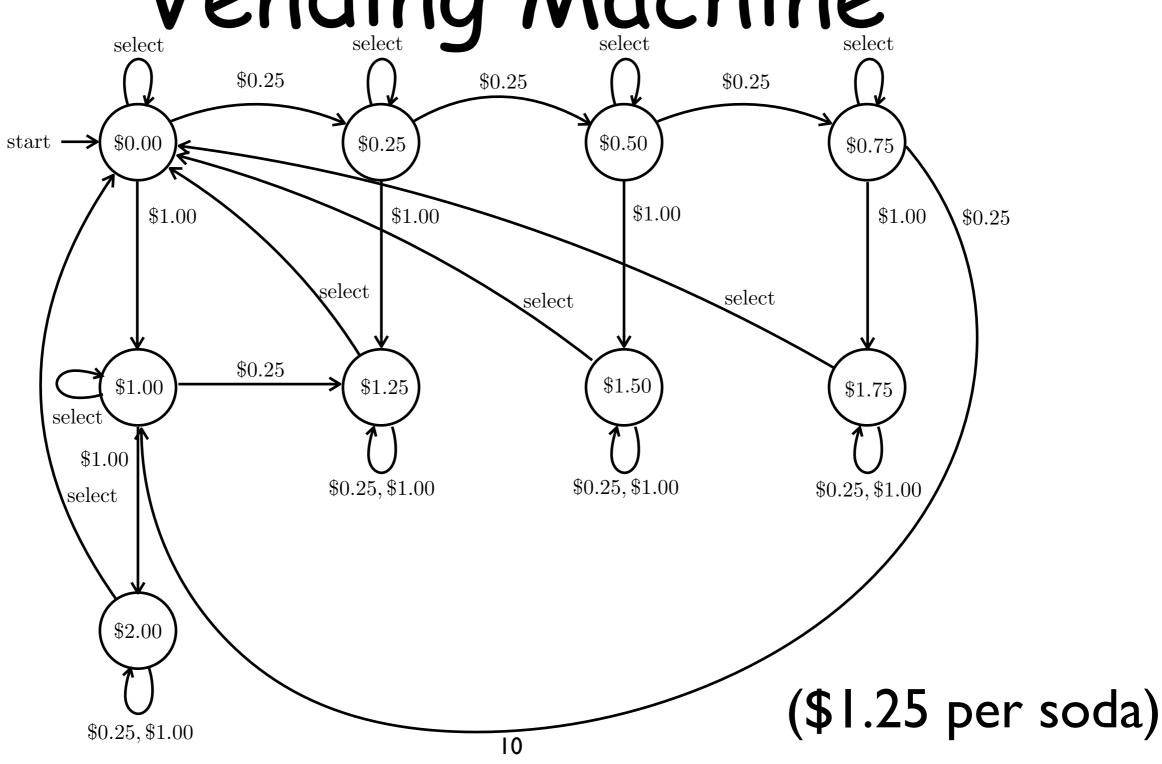
- 1. Identify the admissible **states** of the system (Optional: mark some states as error states)
- 2. Add transitions to move from one state to another (no transition to recover from error states)
- 3. Set the initial state
- 4. (Optional: mark some states as final states)

## Example: Turnstile





# Example: Vending Machine



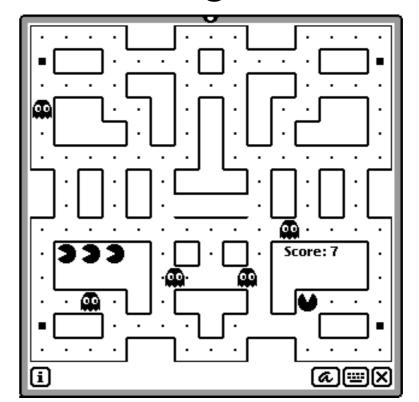
# Computer controlled characters for games

**States** = characters behaviours

**Transitions** = events that cause a change in behaviour

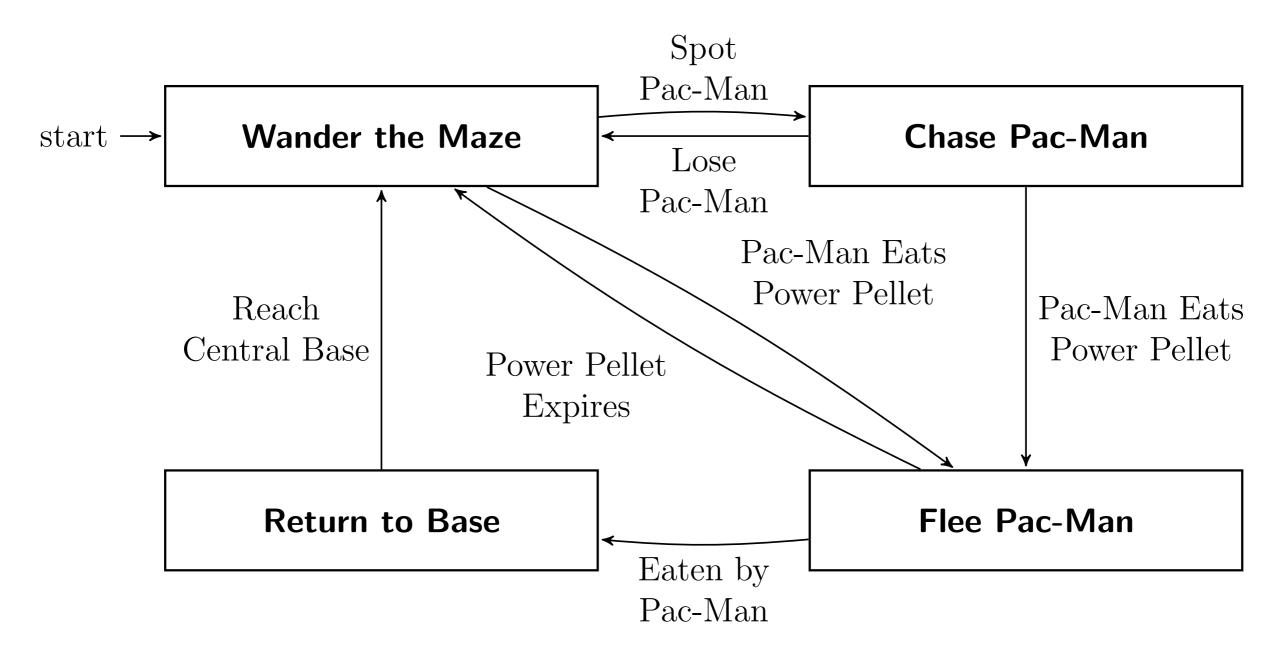
Example:

Pac-man moves in a maze wants to eat pills is chased by ghosts by eating power pills, pac-man can defeat ghosts



## Example: Pac-Man Ghosts





#### Exercises

Without adding states, draw the automata for a SuperGhost that can't be eaten. It chases Pac-Man when the power pill is eaten, and it returns to base if Pac-Man eats a piece of fruit.

Choose a favourite (video) game, and try drawing the state automata for one of the computer controlled characters in that game.

## From automata to Petri nets

#### Some basis

Are you familiar with the following concepts?

```
Set notation \emptyset \quad a \in A \quad A \subseteq B \quad A \times B \quad \wp(A) Functions f: A \to B Predicate logic \mathsf{tt} \quad \mathsf{ff} \quad P \wedge Q \quad P \vee Q \quad \neg P \quad P \to Q \quad \exists x. P(x) \quad \forall x. P(x) Induction principle (base cases + inductive cases) (P(0) \quad \wedge \quad \forall n. (P(n) \Rightarrow P(succ(n)))) \Rightarrow \forall n. P(n)
```

### DFA

A Deterministic Finite Automaton (DFA) is a tuple  $A=(Q,\Sigma,\delta,q_0,F)$ , where

- Q is a finite set of states;
- $\bullet$   $\Sigma$  is a finite set of input symbols;
- $\delta: Q \times \Sigma \to Q$  is the transition function;
- $q_0 \in Q$  is the initial state (also called start state);
- $F \subseteq Q$  is the set of final states (also accepting states)

### Kleene-star notation A\*

Given a set A we denote by  $A^*$  the set of finite sequences of elements in A, i.e.:  $A^* = \{ a_1 \cdots a_n \mid n \geq 0 \land a_1, ..., a_n \in A \}$  We denote the empty sequence by  $\epsilon \in A^*$ 

For example:

$$A = \{\,a,b\,\} \qquad A^* = \{\,\epsilon,a,b,aa,ab,ba,bb,aaa,aab,\dots\}$$

### Inductive definitions

A natural number is either:

- **-** 0
- or the successor n+1 of a natural number n

A sequence over the alphabet *A* is either:

- the empty sequence  $\varepsilon$
- or the juxtaposition wa of a sequence w with an element a of A

## Recursively defined functions

Let us define the exponential function

**base case:** for any natural number k we set exp(k,0) = 1

**inductive case:** for any natural numbers k, n we set  $exp(k,n+1) = exp(k,n) \times k$ 

## Recursively defined functions

Let us define the exponential function

**base case:** for any natural number k we set exp(k,0) = 1

inductive case: for any natural numbers k, n we set  $exp(k,n+1) = exp(k,n) \times k$ 

## Recursively defined functions

Let us define the exponential function

**base case:** for any natural number k we set exp(k,0) = 1

inductive case: for any natural numbers k, n we set  $exp(k, n+1) = exp(k, n) \times k$ 

# Extended transition function (destination function)

Given  $A=(Q,\Sigma,\delta,q_0,F)$ , we define  $\widehat{\delta}:Q\times\Sigma^*\to Q$  by induction:

base case: For any  $q \in Q$  we let

$$\widehat{\delta}(q, \epsilon) = q$$

inductive case: For any  $q \in Q, a \in \Sigma, w \in \Sigma^*$  we let

$$\widehat{\delta}(q, wa) = \delta(\widehat{\delta}(q, w), a)$$

 $(\delta(q, w))$  returns the state reached from q by observing w

# Extended transition function (destination function)

Given  $A=(Q,\Sigma,\delta,q_0,F)$ , we define  $\widehat{\delta}:Q\times\Sigma^*\to Q$  by induction:

base case: For any  $q \in Q$  we let

$$\widehat{\delta}(q, \epsilon) = q$$

inductive case: For any  $q \in Q, a \in \Sigma, w \in \Sigma^*$  we let

$$\widehat{\delta}(q, wa) = \delta(\widehat{\delta}(q, w), a)$$

 $(\delta(q, w))$  returns the state reached from q by observing w

# Extended transition function (destination function)

Given  $A=(Q,\Sigma,\delta,q_0,F)$ , we define  $\widehat{\delta}:Q\times\Sigma^*\to Q$  by induction:

base case: For any  $q \in Q$  we let

$$\widehat{\delta}(q, \epsilon) = q$$

inductive case: For any  $q \in Q, a \in \Sigma, w \in \Sigma^*$  we let

$$\widehat{\delta}(q, wa) = \delta(\widehat{\delta}(q, w), a)$$

 $(\delta(q, w))$  returns the state reached from q by observing w

## String processing

Given  $A=(Q,\Sigma,\delta,q_0,F)$  and  $w\in\Sigma^*$  we say that A accept w iff

$$\widehat{\delta}(q_0, w) \in F$$

The **language** of  $A = (Q, \Sigma, \delta, q_0, F)$  is

$$L(A) = \{ w \mid \widehat{\delta}(q_0, w) \in F \}$$

## Transition diagram

We represent  $A=(Q,\Sigma,\delta,q_0,F)$  as a graph s.t.

- Q is the set of nodes;
- $\{q \xrightarrow{a} q' \mid q' = \delta(q, a)\}$  is the set of arcs.

Plus some graphical conventions:

- ullet there is one special arrow Start with  $\stackrel{Start}{\longrightarrow} q_0$
- ullet nodes in F are marked by double circles;
- ullet nodes in  $Q\setminus F$  are marked by single circles.

# String processing as paths

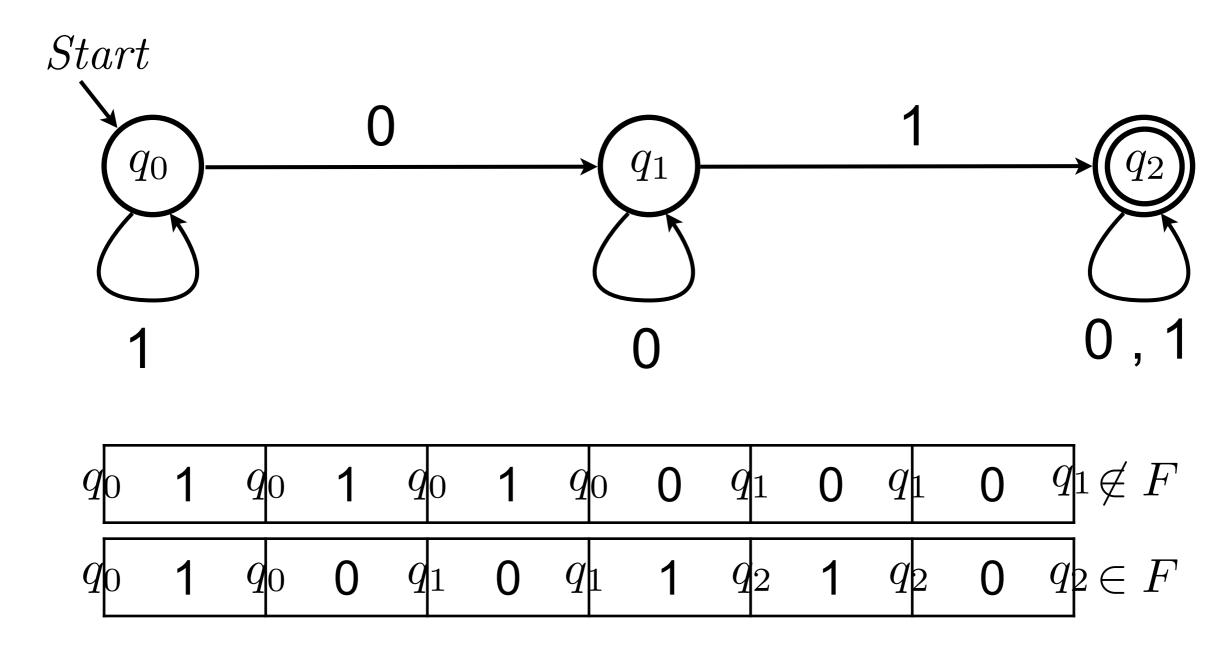
A DFA accepts a string w, if there is a path in its transition diagram such that:

it starts from the initial state

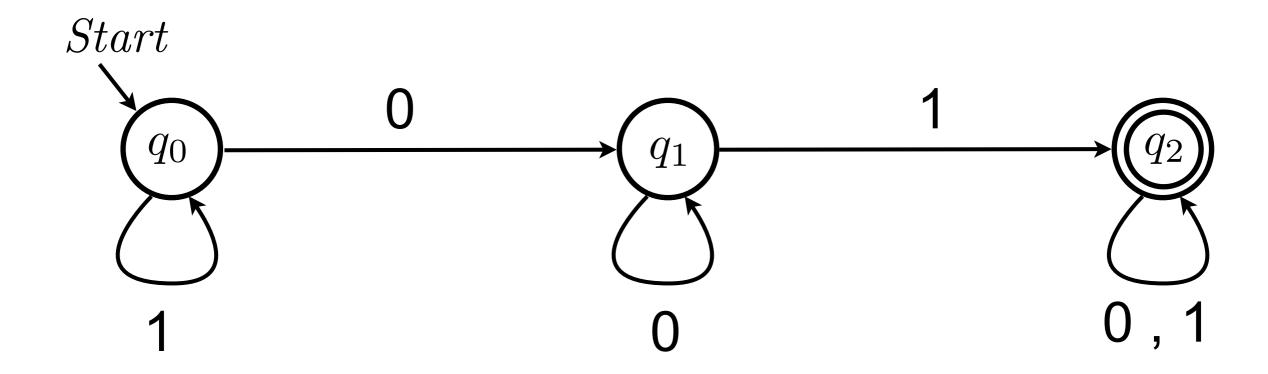
it ends in one final state

the sequence of labels in the path is exactly w

## DFA: example



## DFA: question time



Does it accept 100?

Does it accept 011?

Does it accept 1010010?

What is L(A)?

#### Transition table

Conventional tabular representation

its rows are in correspondence with states

its columns are in correspondence with input symbols

its entries are the states reached after the transition

Plus some decoration

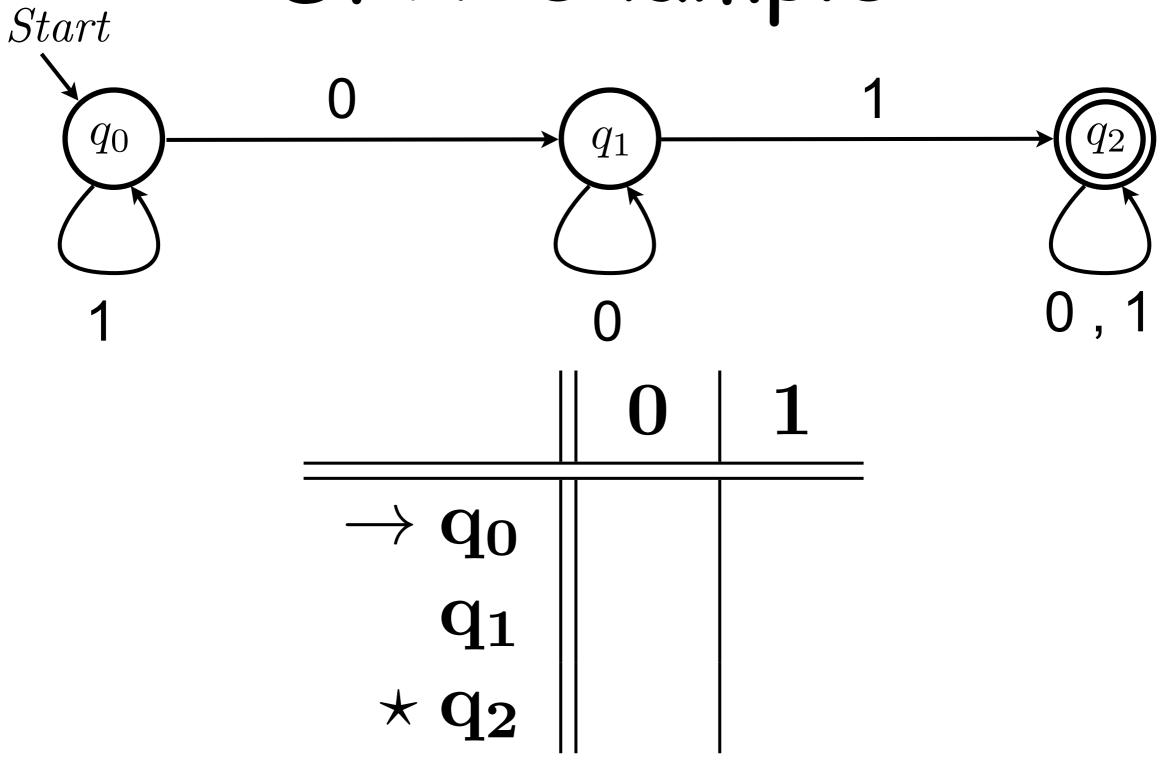
start state decorated with an arrow

all final states decorated with \*

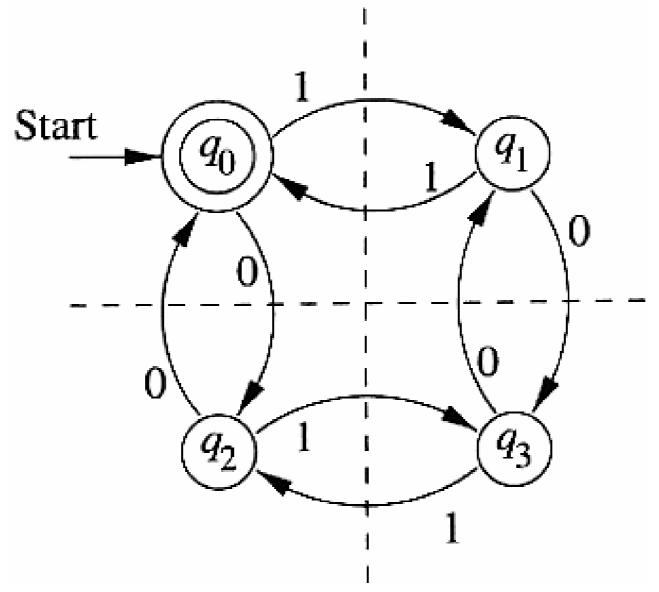
### Transition table

			a		
$\rightarrow$					
	$\mathbf{q}$		$\delta(q,a)$		
*					
*					

## DFA: example



### DFA: exercise



Does it accept 100? Write its transition table.

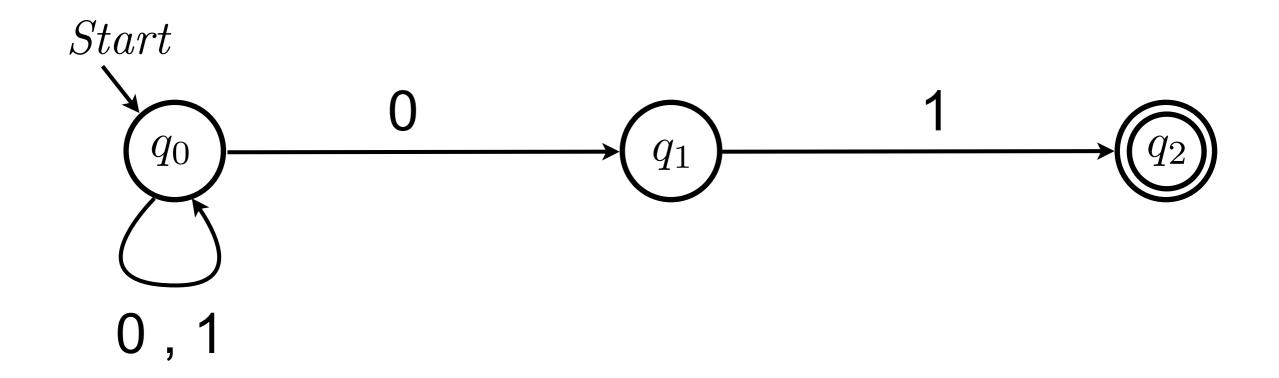
Does it accept 1010? What is L(A)?

#### NFA

A Non-deterministic Finite Automaton (NFA) is a tuple  $A=(Q,\Sigma,\delta,q_0,F)$ , where

- Q is a finite set of states;
- $\Sigma$  is a finite set of input symbols;
- $\bullet \ \delta: Q \times \Sigma \to \wp(Q) \ \text{is the transition function;}$
- $q_0 \in Q$  is the initial state (also called start state);
- $F \subseteq Q$  is the set of final states (also accepting states)

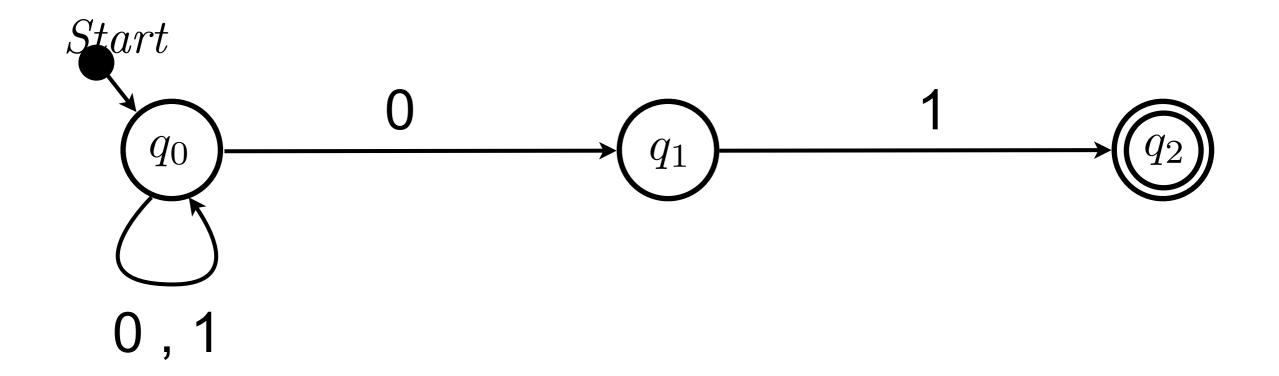
## NFA: example



Can you explain why it is not a DFA?

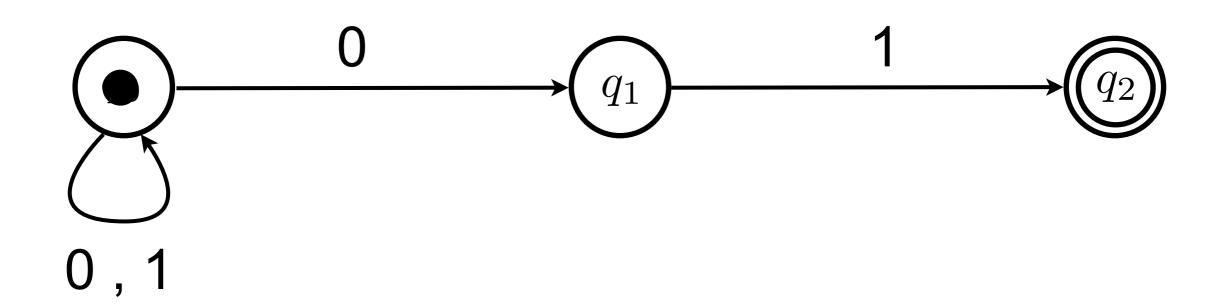
## Reshaping

#### Step 1: get a token

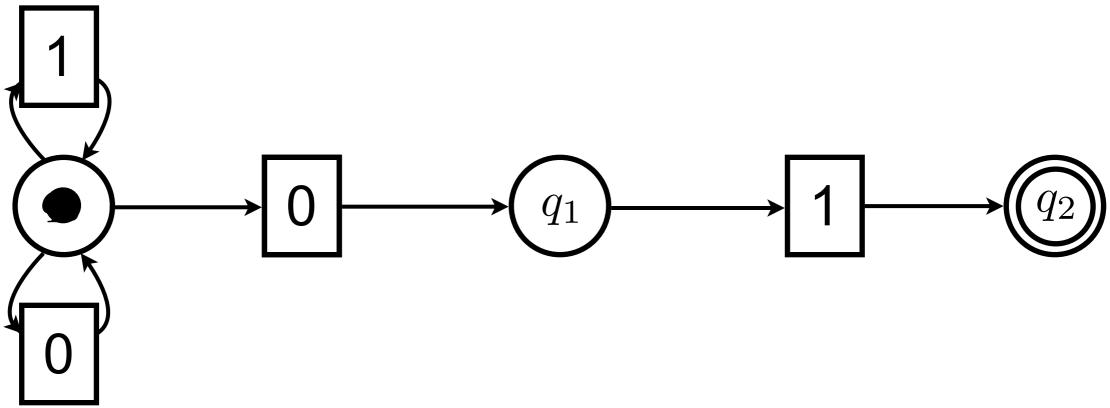


0 1 0 1

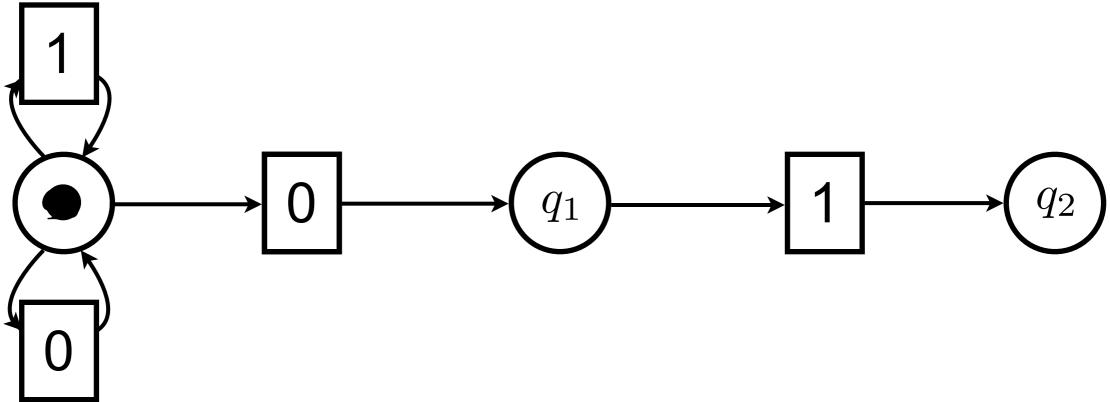
# Step 2: forget initial state decoration



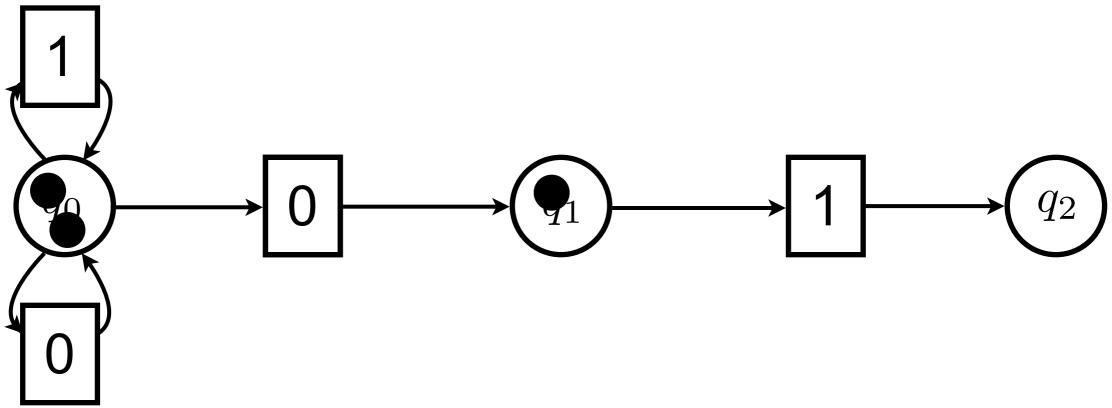
# Step 3: transitions as boxes

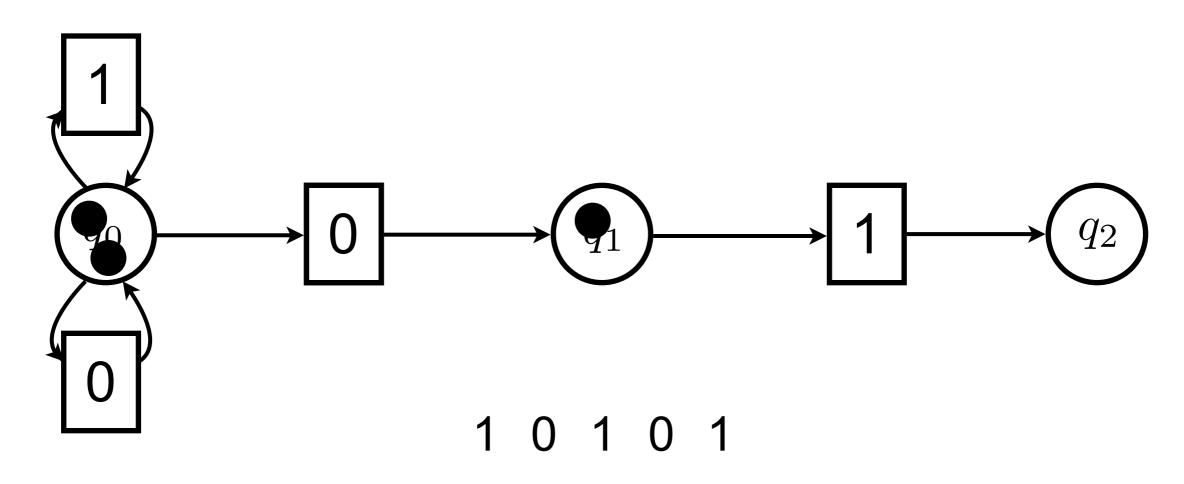


# Step 4: forget final states

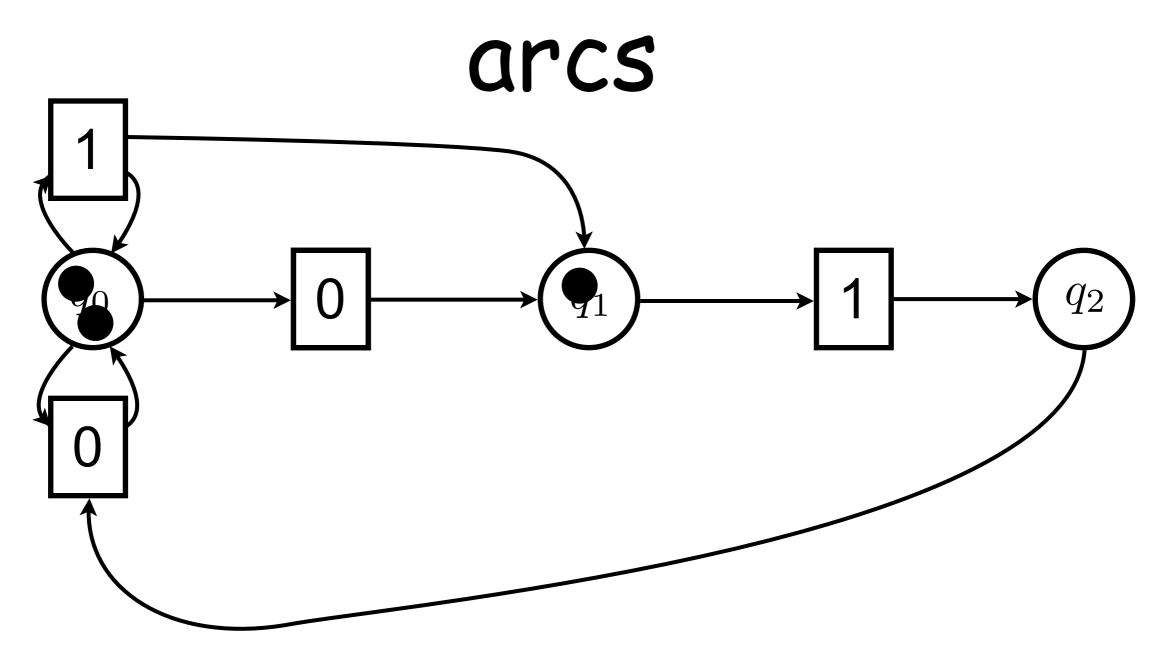


# Step 5: allow for more tokens

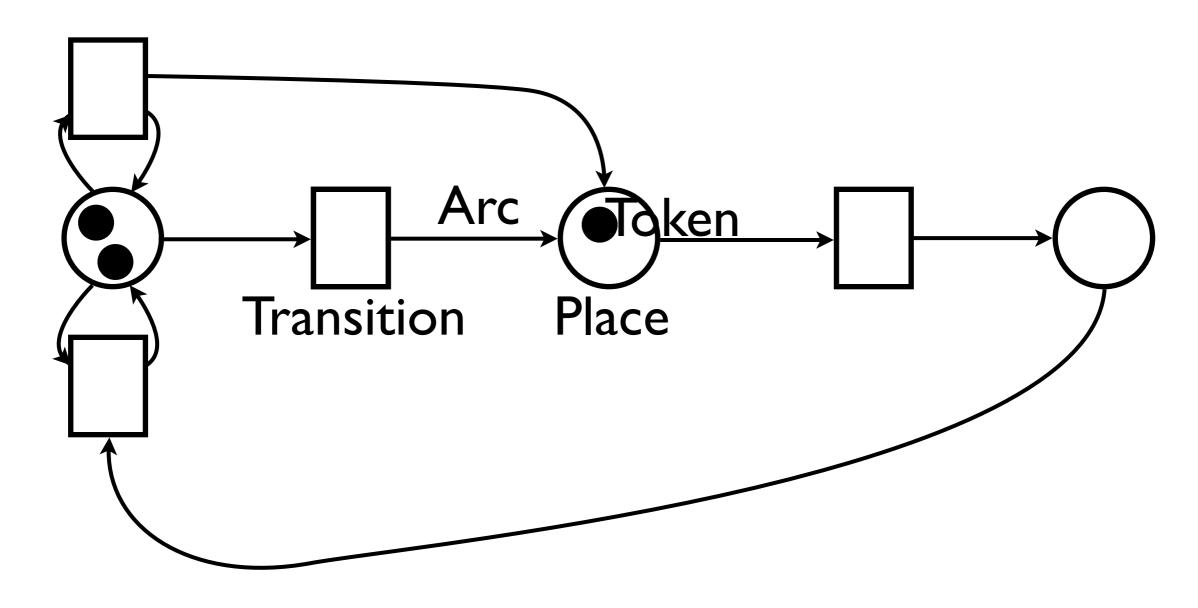


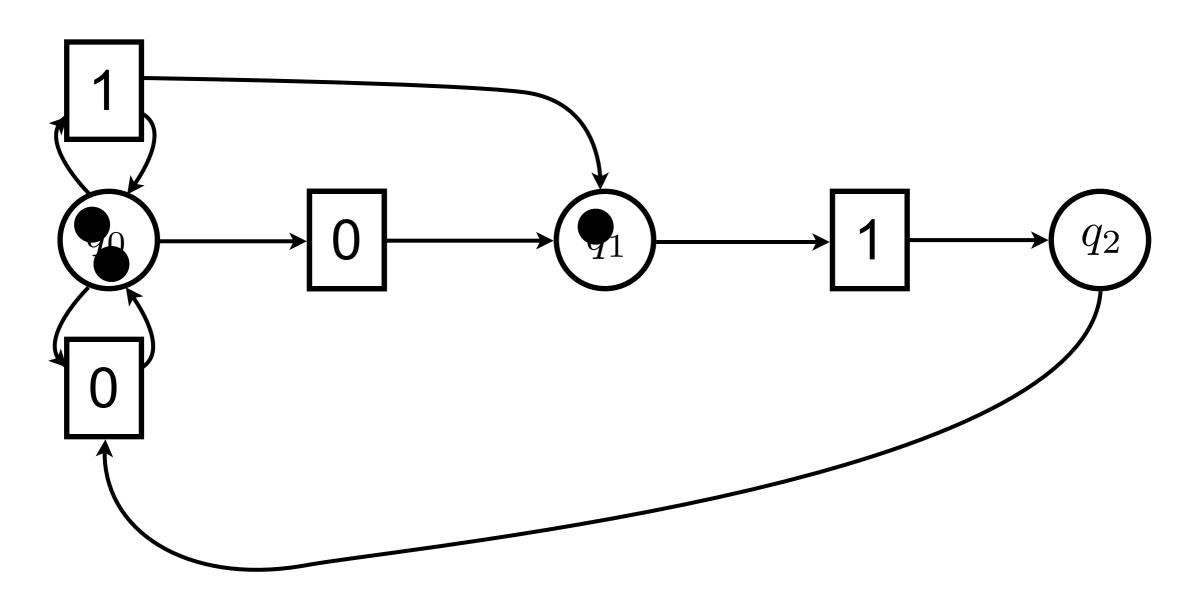


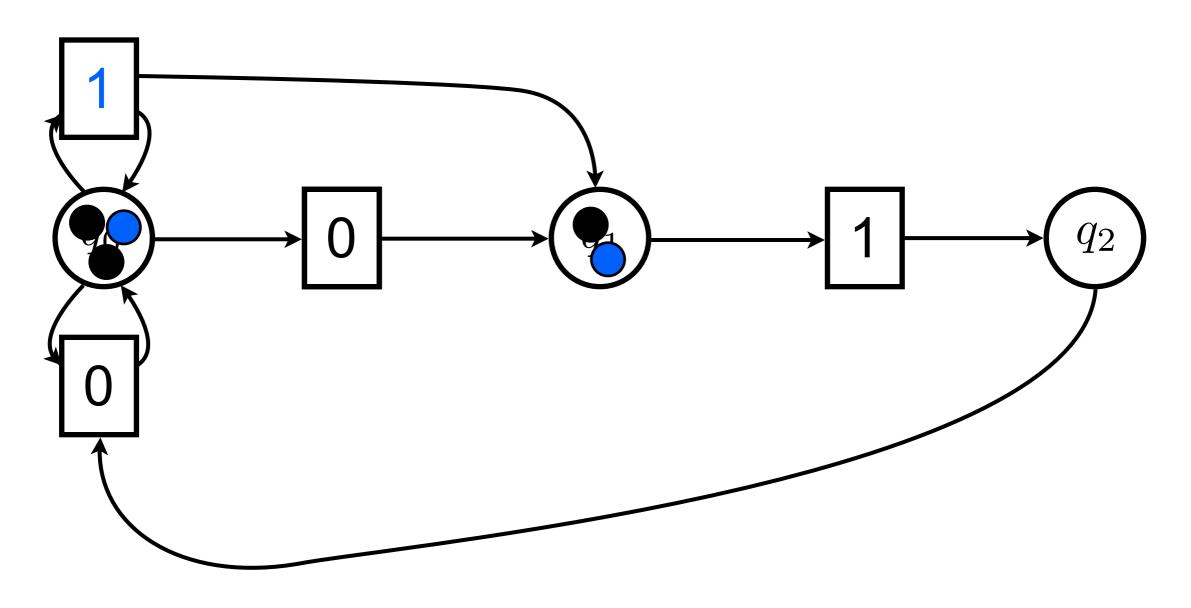
### Step 6: allow for more

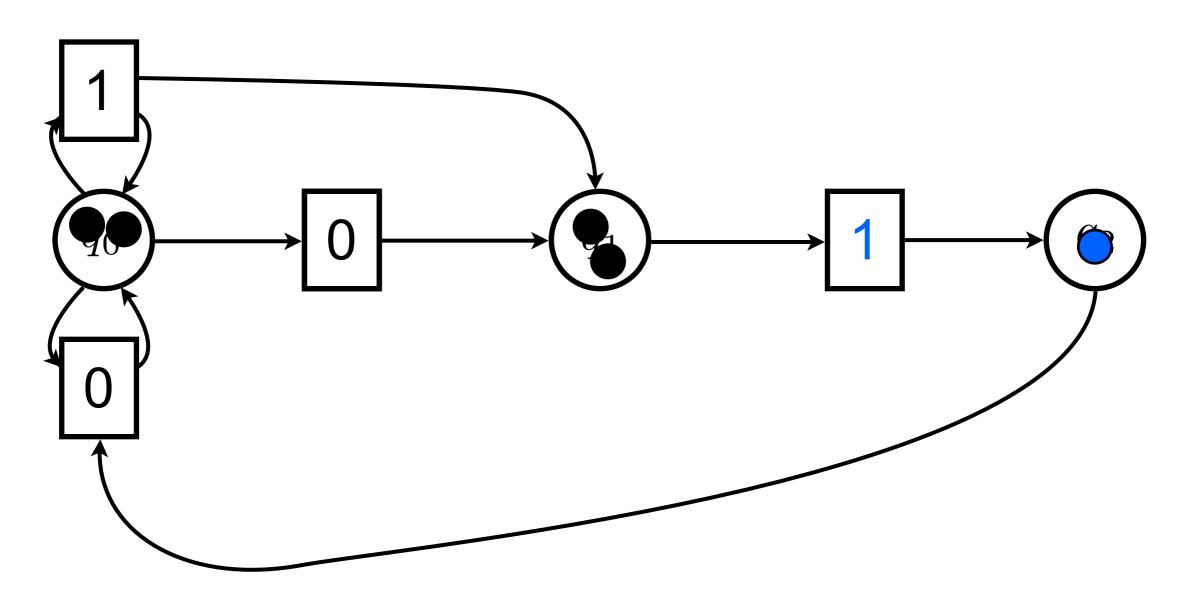


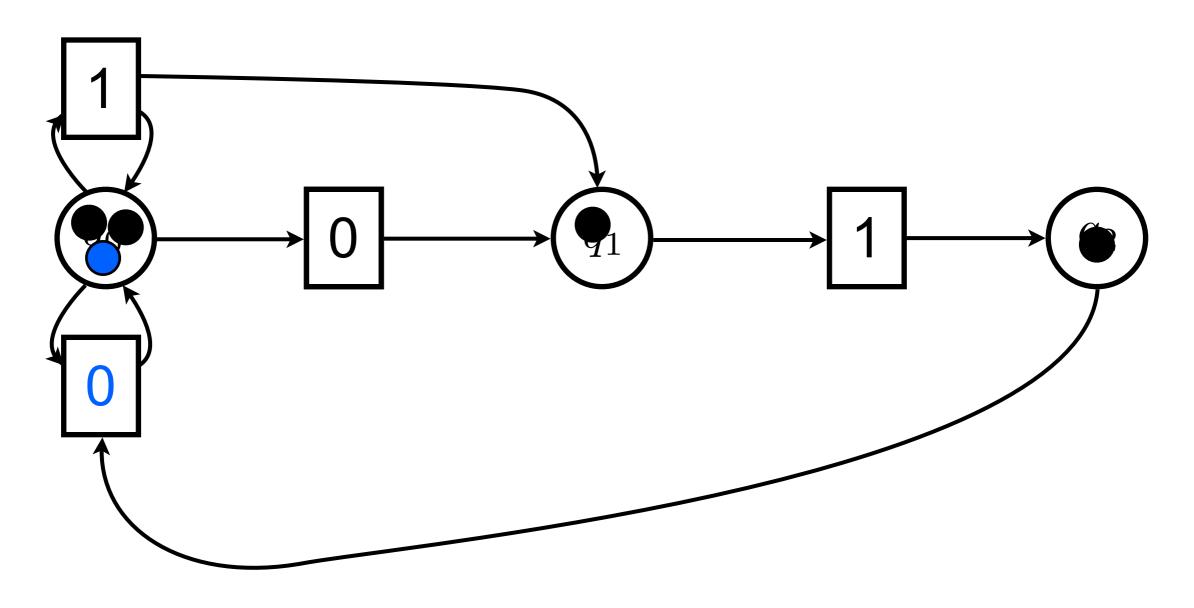
#### Terminology

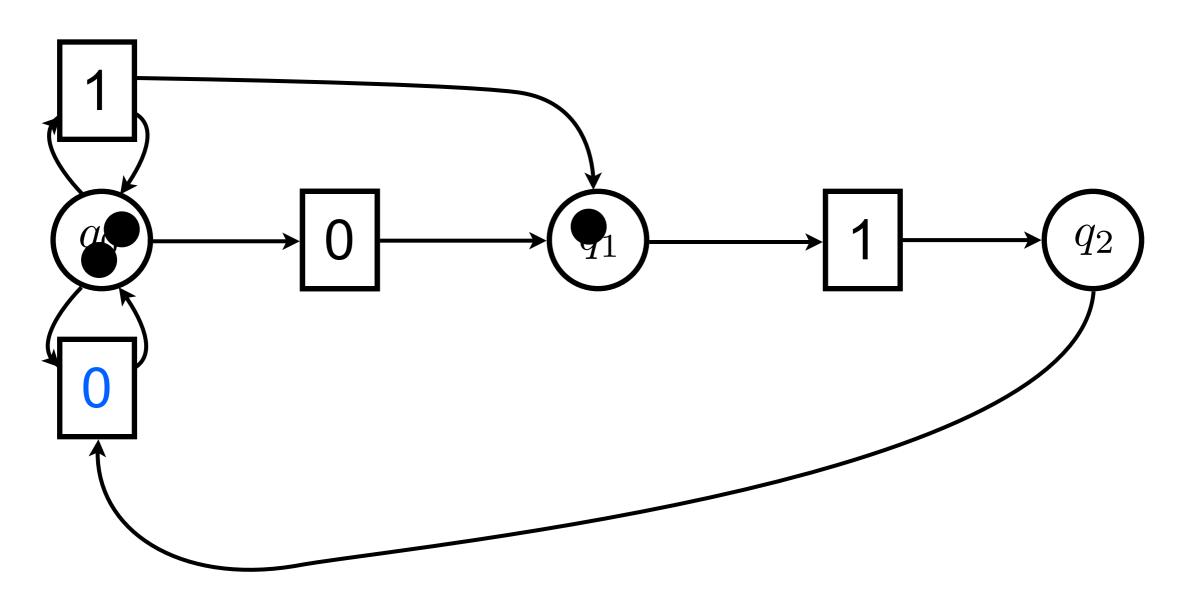












#### Some hints

Nets are **bipartite graphs**: arcs never connect two places arcs never connect two transitions

Static structure for dynamic systems: places, transitions, arcs do not change tokens move around places

Places are passive components

Transitions are active components:
tokens do not flow!

(they are removed or freshly created)