

# Laurea Magistrale in INFORMATICA

## Principi di Linguaggi di Programmazione

### Compilatori

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Appello III - June 4th, 2013

(Timing: 2 hours – Grading: (pts n-m) is the score range to be obtained in each exercise)

**Exercise 1.** (pts 3 – 5) Let  $E \equiv a(a^* | b^*)b$  be a regular expression.

- Give the dotted automaton of  $E$  (show the computation and the set of items of each state);
- By using the minimization algorithm, prove the minimality of the automaton that has been obtained in (a).

**Exercise 2.** (pts 5 - 10)

- Compute the Canonical Collection,  $Coll(1)$ , of the LR(1) parser of the grammar  $G$  below:  
 $S ::= aSS | Sb | c$
- Give the Parsing Table of the LALR(1) parser of  $G$
- Show the behaviour of the shift/reduce automaton during the analysis of:  $acacbc$ .

**Exercise 3.** (pts 7 - 15) Let  $G$  be an LR grammar for Boolean expressions with *disjunction*, *\_or\_*, *negation*, *not\_*, *conditional*, *\_?:\_*, grouping, variables and the literals *true*, *false*. All the operators have left associativity and precedence as follow:  $? > \text{not} > \text{or}$ .

- Define  $G$  and show that it recognizes the expression:  $x \text{ or } \text{not } y \text{ ? } \text{not } \text{not } y : z$
- Give an oblivious, ascendant, translation scheme for the generation of 3AC code with  $loc$  as the invariant.
- Give an oblivious, ascendant, translation scheme for the generation of 3AC code with target-uncomplete statement lists (short-circuit)
- Apply the scheme in (b) in order to provide the code generation of the expression:  
 $x \text{ or } \text{not } y \text{ ? } \text{not } \text{not } y : z$ .
- Apply the scheme in (c) in order to provide the code generation of the expression:  
 $x \text{ or } \text{not } y \text{ ? } \text{not } \text{not } y : z$ ,

also showing the value of the list the two attributes of the root of the expression parse-tree. Assume that the following operators and constants be available in 3AC: [or] for *\_or\_*, [not] for *not\_*, #T for true and #F for false. Finally, assume the following association in symbol table:  $loc_x$  for  $x.loc$ ,  $loc_y$  for  $y.loc$ ,  $loc_z$  for  $z.loc$ .