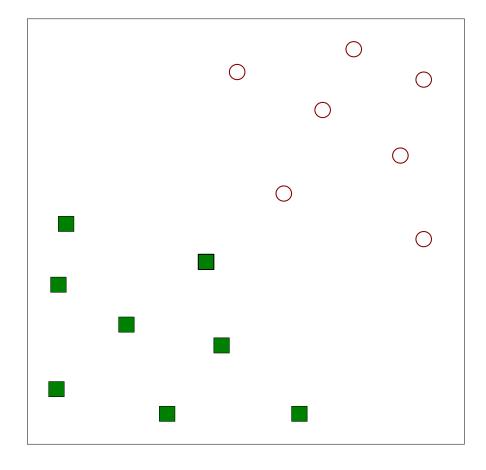
# Support Vector Machine



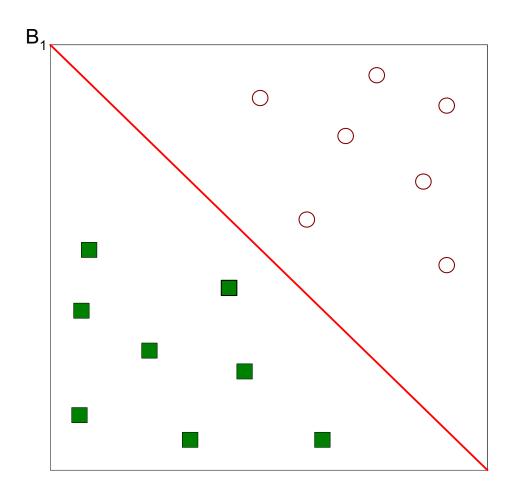
 Binary classification can be viewed as the task of separating classes in feature space

• Find a linear hyperplane (decision boundary) that separates the data.

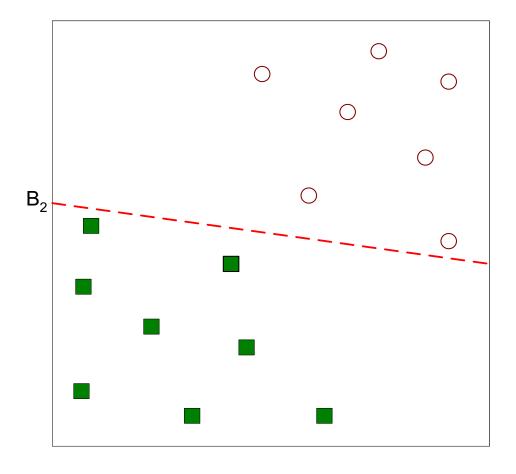


## Maximum Margin Hyperplanes

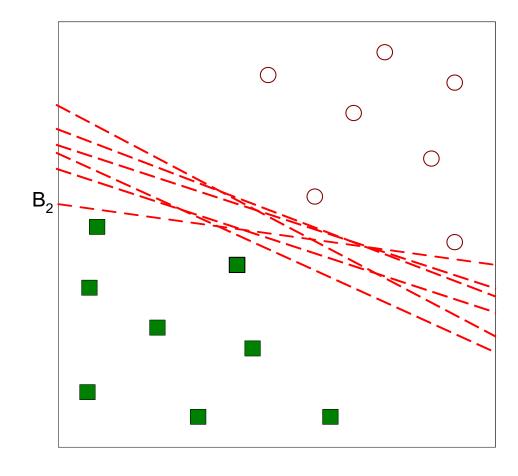
• One possible solution.



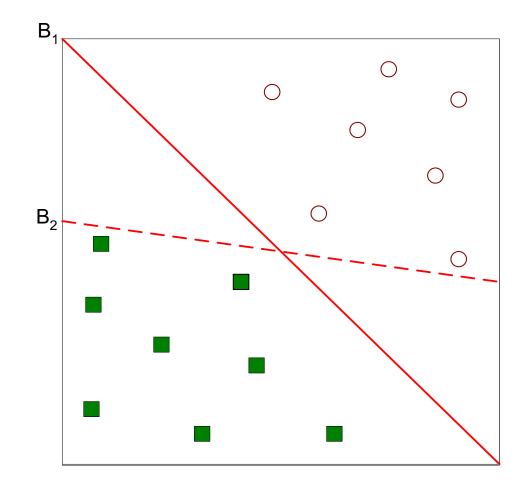
• Another possible solution.



• Other possible solutions.



- Let's focus on B<sub>1</sub> and B<sub>2</sub>.
- Which one is better?
- How do you define better?



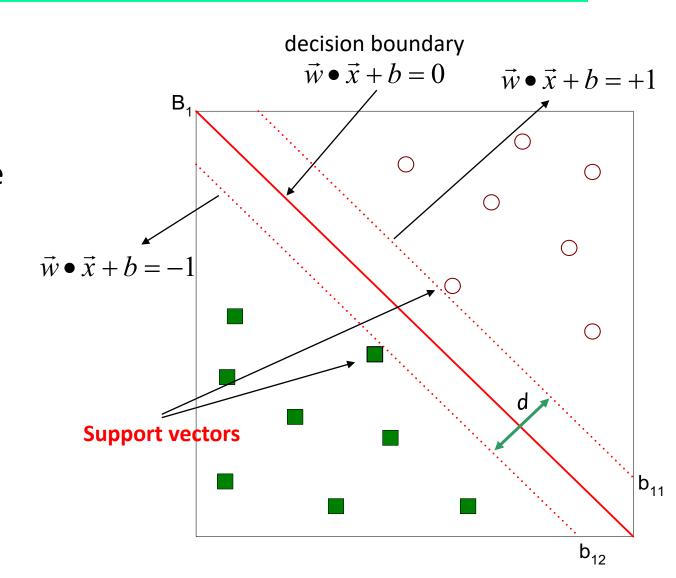
### Support Vector Machine (SVM)

• SVM represents the decision boundary using a subset of the training examples, known as the **support vectors**.

• SVM is based on the concept of maximal margin hyperplane

#### Classification Margin

- Decision Boundary is associated to 2 hyperplanes obtained by super vectors
- Examples closest to the hyperplane are *support vectors*.
- *Margin d* of the separator is the distance between support vectors.



### Linear SVM: Separable Case

$$\vec{w} \bullet \vec{x} + b = +1$$

• A linear SVM is a classifier that searches for a hyperplane with the largest margin (a.k.a. maximal margin classifier).

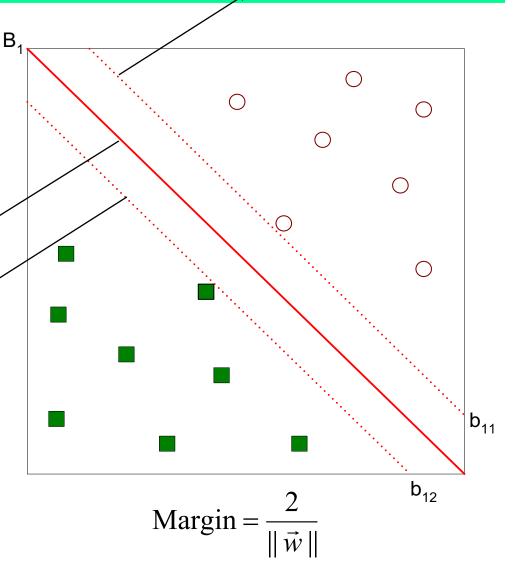
• w and b are parameters.

decision boundary  $\vec{w} \cdot \vec{x} + b = 0$ 

$$\vec{w} \bullet \vec{x} + b = -1$$

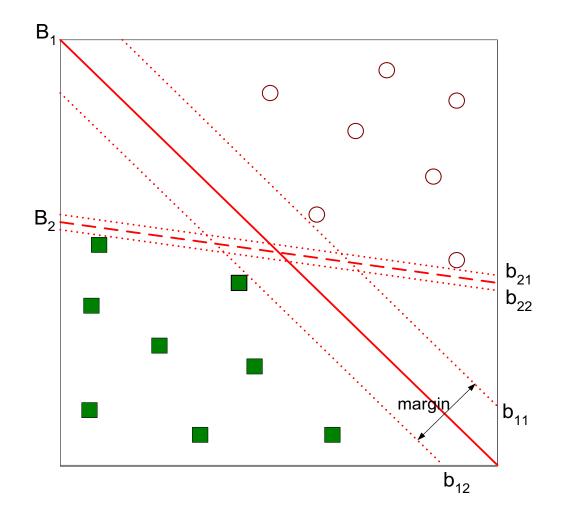
Given w and b the classifier works as

$$f(\vec{x}) = \begin{cases} 1 & \text{if } \vec{w} \bullet \vec{x} + b \ge 1 \\ -1 & \text{if } \vec{w} \bullet \vec{x} + b \le -1 \end{cases}$$



#### Maximum Margin Hyperplanes

- The best solution is the hyperplane that **maximizes** the **margin**.
- Thus, B<sub>1</sub> is better than B<sub>2</sub>.



#### Learning a Linear SVM

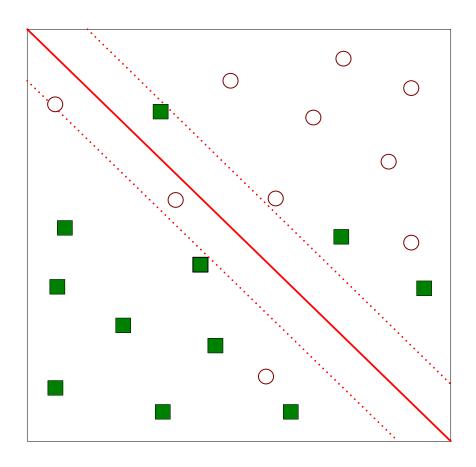
- Learning the model is equivalent to determining w and b.
- How to find w and b?
- Objective is to maximize the margin by minimizing  $L(\vec{w}) = \frac{\|\vec{w}\|^2}{2}$
- Subject to to the following constraints

$$y_i = \begin{cases} 1 & \text{if } \vec{\mathbf{w}} \bullet \vec{\mathbf{x}}_i + b \ge 1 \\ -1 & \text{if } \vec{\mathbf{w}} \bullet \vec{\mathbf{x}}_i + b \le -1 \end{cases}$$

 This is a constrained optimization problem: a Quadratic optimization problem, a well-known class of mathematical programming problem, and many algorithms exist for solving them (with many special ones built for SVMs)

### Linear SVM: Nonseparable Case

• What if the problem is not linearly separable?

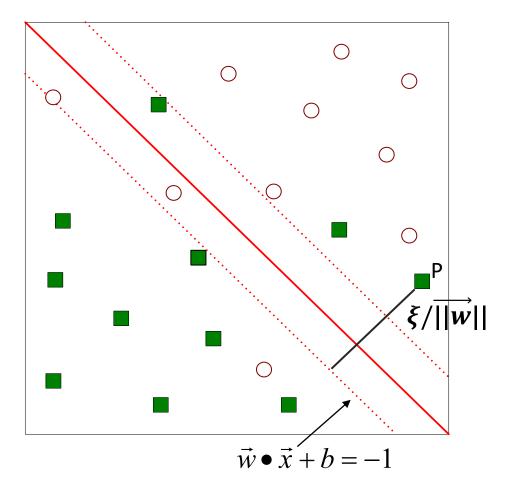


#### Slack Variables

- The inequality constraints must be relaxed to accommodate the nonlinearly separable data.
- This is done introducing slack variables  $\xi$  into the constrains of the optimization problem

$$y_i = \begin{cases} 1 & \text{if } \vec{\mathbf{w}} \bullet \vec{\mathbf{x}}_i + b \ge 1 - \xi_i \\ -1 & \text{if } \vec{\mathbf{w}} \bullet \vec{\mathbf{x}}_i + b \le -1 + \xi_i \end{cases}$$

•  $\xi$  provides an estimate of the error of the decision boundary on the misclassified training examples.



#### Learning a Nonseparable Linear SVM

• Objective to minimize

$$L(w) = \frac{\|\vec{w}\|^2}{2} + C\left(\sum_{i=1}^{N} \xi_i^k\right)$$

• Subject to to the constraints

$$y_i = \begin{cases} 1 & \text{if } \vec{\mathbf{w}} \bullet \vec{\mathbf{x}}_i + \mathbf{b} \ge 1 - \xi_i \\ -1 & \text{if } \vec{\mathbf{w}} \bullet \vec{\mathbf{x}}_i + \mathbf{b} \le -1 + \xi_i \end{cases}$$

 where C and k are user-specified parameters representing the penalty of misclassifying the training instances

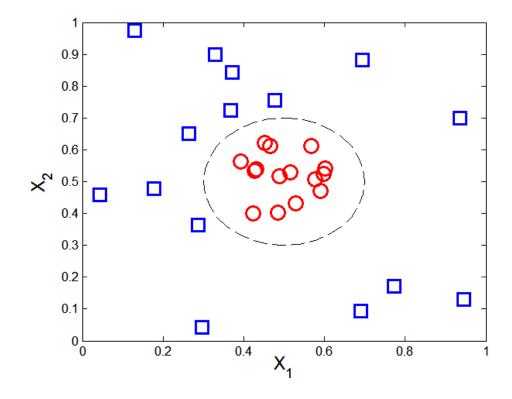
C is a regularization parameter and allows to control overfitting:

- small C allows constraints to be easily ignored → large margin
- large C makes constraints hard to ignore → narrow margin
- C = ∞ enforces all constraints: hard margin

#### Nonlinear SVM

• What if the decision boundary is not linear?

$$y(x_1, x_2) = \begin{cases} 1 & \text{if } \sqrt{(x_1 - 0.5)^2 + (x_2 - 0.5)^2} > 0.2 \\ -1 & \text{otherwise} \end{cases}$$

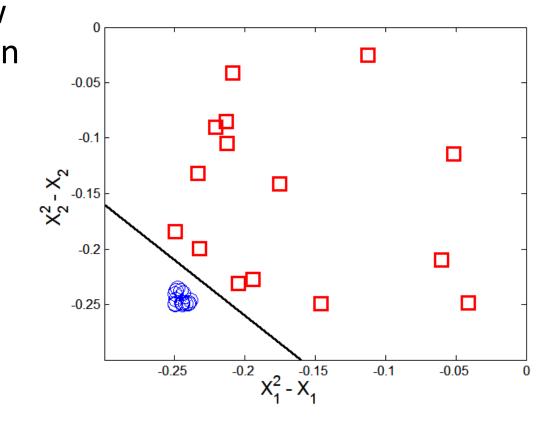


#### Nonlinear SVM

• The trick is to transform the data from its original space x into a new space  $\Phi(x)$  so that a linear decision boundary can be used.

$$\begin{split} x_1^2 - x_1 + x_2^2 - x_2 &= -0.46. \\ \Phi : (x_1, x_2) &\longrightarrow (x_1^2, x_2^2, \sqrt{2}x_1, \sqrt{2}x_2, 1). \\ w_4 x_1^2 + w_3 x_2^2 + w_2 \sqrt{2}x_1 + w_1 \sqrt{2}x_2 + w_0 &= 0. \end{split}$$

• Decision boundary  $\vec{w} \bullet \Phi(\vec{x}) + b = 0$ 



#### References

Support Vector Machine (SVM). Chapter
5.5. Introduction to Data Mining.

